

GPS Engine Board

EB-250/ EB-250L

EB-250 is an ultra miniature 13 x 15 mm² GPS engine board. It provides superior navigation performance under dynamic conditions in areas with limited sky view like urban canyons. High sensitivity up to **-158dBm** for weak signal operation without compromising accuracy. EB-250 series are your best choice for embedded applications.



Key Features :

- Small form factor: 13 x 15 x 2.2 mm
- Lead-Free – RoHS/WEEE compliant
- High sensitivity -158dBm
- Tracks 51-Channel of satellites
- Fast Position Fix
- Low power consumption
- Max. GPS signal input level :
EB-250 -120dBm
EB-250L -117dBm

Applications :

- Handheld devices
- Automotive and Marine Navigation
- Automotive Navigator Tracking
- Emergency Locator
- Geographic Surveying
- Personal Positioning
- Sporting and Recreation
- Embedded applications : PDA, DSC, Smart phone, UMPC, PND, MP4

PIN Definition :

1	RX1	GND	22
	TX1	RF_INPUT	
	PPS	GND	
	TX0	V285A	
	RX0	NC	
	GND	GND	
	GPIO[8]	GPIO[5]	
	GPIO[0]	GPIO[7]	
	GPIO[4]	GPIO[6]	
	V285D	VIN_3V3	
11	ON/OFF	V_RTC_3V3	12

PIN Coordinates Unit:mm

Pin #	X	Y	Pin #	X	Y
1	0.00	0.00	12	13.0	12.7
2	0.00	1.27	13	13.0	11.43
3	0.00	2.54	14	13.0	10.16
4	0.00	3.81	15	13.0	8.89
5	0.00	5.08	16	13.0	7.62
6	0.00	6.35	17	13.0	6.35
7	0.00	7.62	18	13.0	5.08
8	0.00	8.89	19	13.0	3.81
9	0.00	10.16	20	13.0	2.54
10	0.00	11.43	21	13.0	1.27
11	0.00	12.7	22	13.0	0.00



TRANSYSTEM INC.

An A+ supplier of RF microwave & GPS products

Ultimate

EB

Ver 1.3

8029605001A

EB-250 Specifications

Specification	Description
General	L1 frequency, C/A code (SPS) 51 independent tracking channels
Sensitivity	-158dBm /Tracking; -146dBm /Acquisition
Update Rate	Up to 5Hz
Accuracy	Without aid: 3.0m 2D-RMS <3m CEP (50%) without SA (horizontal) DGPS (WAAS, EGNOS, MSAS, RTCM): 2.5m
Acquisition (open sky)	Cold Start: 36 sec Warm Start: 33 sec Hot Start: 1 sec
Reacquisition	< 1sec
Dynamics	Altitude: 18000m (max.) Velocity: 515m/sec (max.) Vibration: 4G (max.)
Supply Voltage	DC 3.0~6 V
Power Consumption	EB-250: < 30mA @ 2.85V (w/o Active ANT) / Tracking EB-250L: < 27.5mA @ 2.85V (w/o Active ANT) / Tracking
Backup Battery	DC 1.5~6V (RTC Vcc)
NMEA Message	NMEA0183 v3.1 baud rate 4800/9600/.../57600, default 9600 Selectable Output: GGA, GLL, GSA, GSV, RMC, and VTG
Datum	Default WGS-84 (total 219 Datum)
Antenna	External Antenna / External Active Antenna Output Voltage: 2.85 VDC
Serial Interface	TTL
Operating Temperature	-30°C to 85°C
Storage Temperature	-40°C to 125°C
Operating Humidity	≤95%, non condensing
Mounting	SMT Type, 22 Pin
Dimension	13 x 15 x 2.2(H) mm

*Specifications subject to change without prior notice.
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1 Introduction

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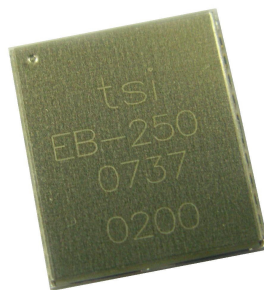
1.1 Key Features

- Small form factor: 13 x 15 x 2.2 mm
- Lead-Free – RoHS/WEEE compliant
- High sensitivity -158dBm
- Tracks 51-Channel of satellites
- Fast Position Fix, 36/ 33/ 1s for Cold/ Warm/ Hot start
- Low power consumption

1.2 Applications

- Handheld devices
- Automotive and Marine Navigation
- Automotive Navigator Tracking
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- Embedded applications such as: PDA, DSC, Smart phone, UMPC, PND, MP4

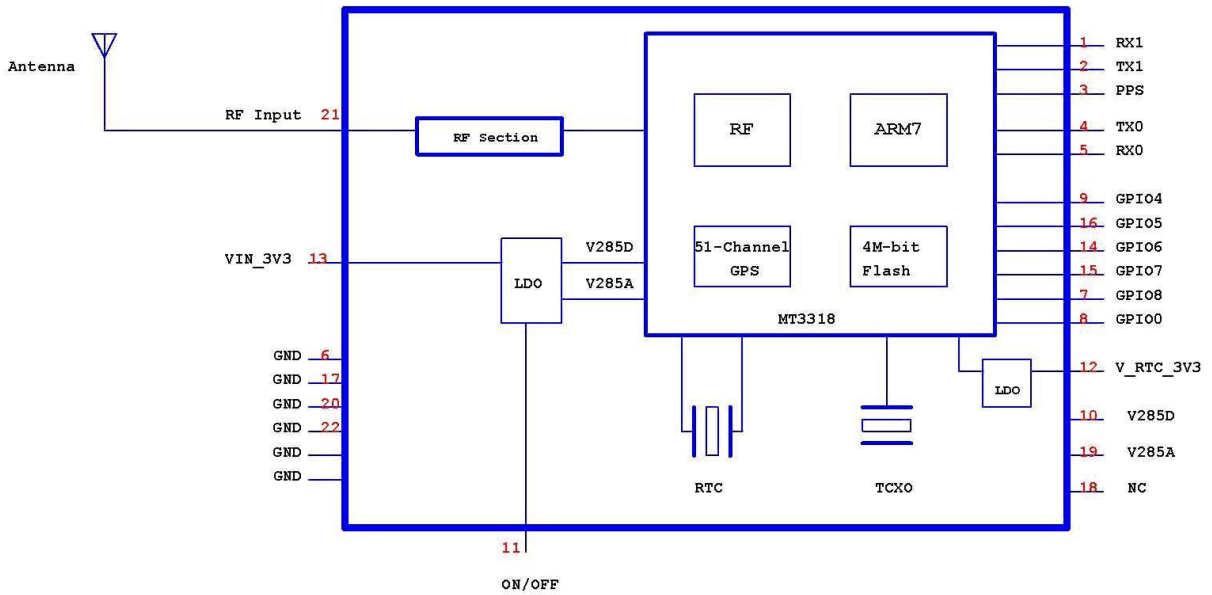
1.3 Look & Feel



2 Technical Description

2.1 Block Diagram

EB-250 Series System Block Diagram



2.2 Pin Definition

Pin#	Signal Name	Type	Description
1	RX1	I	Serial Data Input
2	TX1	O	Serial Data Output
3	PPS	O	1Hz pulse 10% duty cycle when GPS has position fix
4	TXD	O	Serial data Output (NMEA)
5	RXD	I	Serial Data Input (NMEA)
6	GND	P	Ground
7	GPIO[8]	I/O*	General input/ output
8	GPIO[0]	O	GPS status, blink when GPS has position fix
9	GPIO[4]	I/O*	General input/ output
10	V285D	P	Digital power indicator, 2.85V±2%
11	On / Off	I	GPS Power On / Off control , Open if not used
12	V_RTC_3V3	P	RTC power 1.5~6V DC, 500uA max
13	VIN_3V3	P	Power Supply 3.0~6V DC
14	GPIO[6]	I/O*	General input / output
15	GPIO[7]	I/O*	General input / output
16	GPIO[5]	I/O*	General input / output
17	GND	P	Ground
18	NC	NC	NC
19	V285A	P	Analog power indicator, 2.85V±2%
20	GND	P	Ground
21	RF Input	I	Antenna port, L1, 1575.42MHz, 50 ohm
22	GND	P	Ground

P: Power I: Input O: Output I/O*: Input or Output, Open if not used

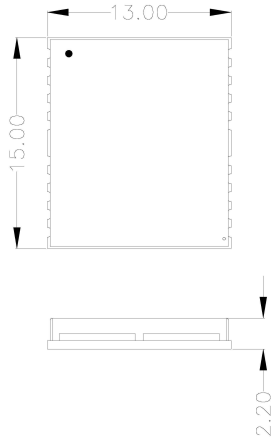
2.3 Specification

EB-250 Specifications

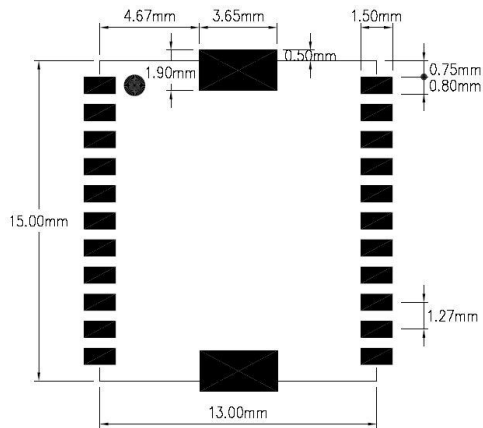
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Mounting	SMT Type, 22 Pin
Dimension	13 x 15 x 2.2(H) mm

3 Dimension and Package

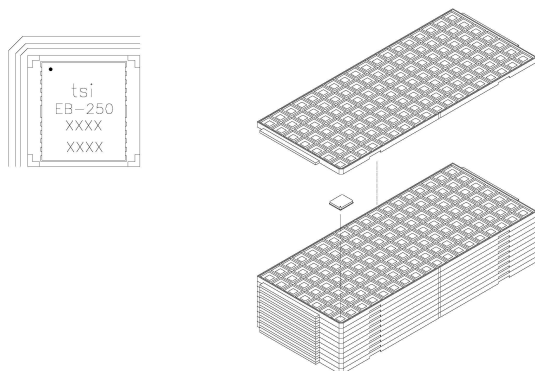
3.1 Mechanical Dimension



3.2 Recommend Layout Pattern



3.3 Package



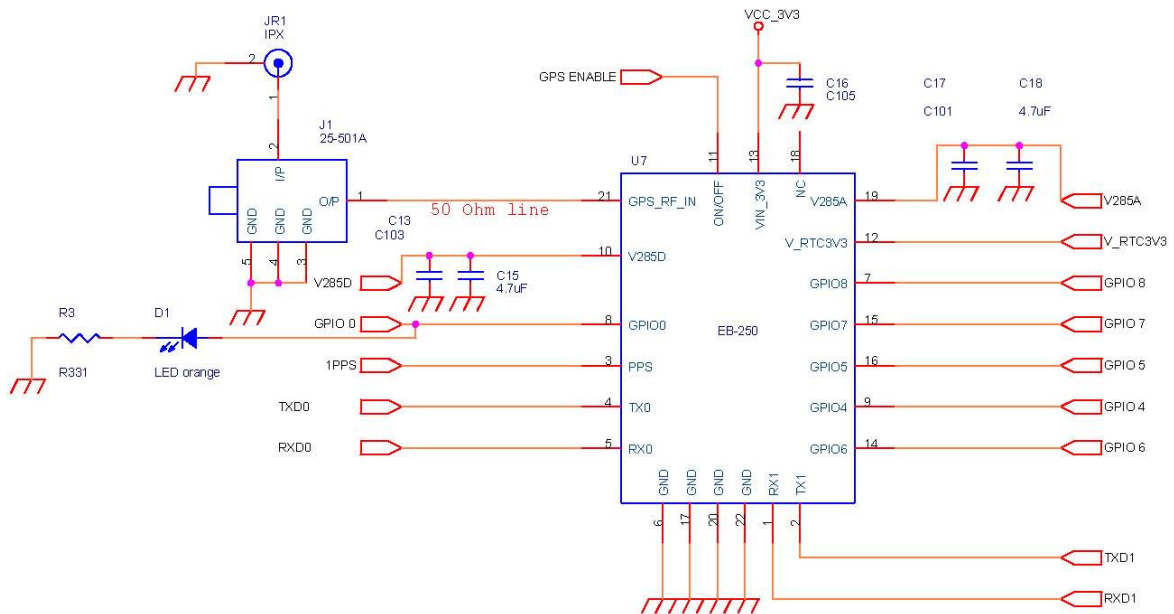
4 Application Information

4.1 GPS Antenna Recommendations

Follow below recommendations when choosing GPS antenna for EB-250 series for best system performance. Transystem also offers active antenna products for optimal performance with EB-250 series. For details, please contact your Transystem sales contact directly.

- Use active antenna that works with 3V power supply
- Receiving frequency $1575.42 \pm 1.032\text{MHz}$
- Polarization RHCP (right hand circular polarized)
- Output impedance = 50 Ohm
- $15\text{dB} \leq \text{LNA Gain} \leq 20\text{dB}$
- Noise figure $\leq 2.0\text{dB}$
- Connector: surface mounted on main PCB, Ipex or MMCX

4.2 Application Circuit



【Note1】 : GPIO[0] (pin#8) can be used as GPS position fix indicator.

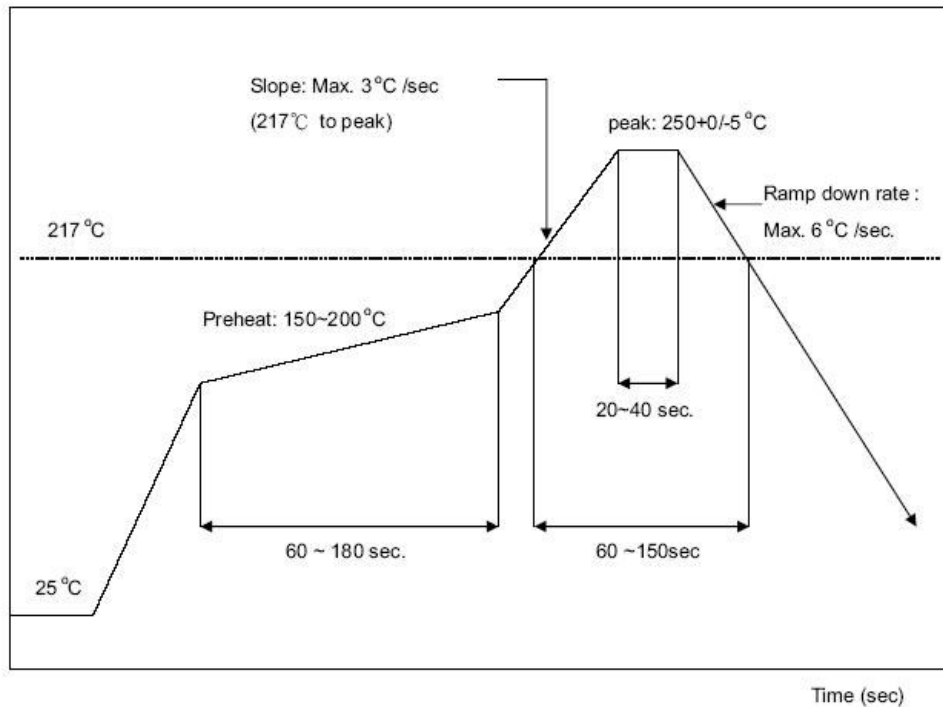
【Note2】 : V_RTC_3V3 (pin#12) could connect to 1.5~6V DC power supply directly.

4.3 General GPS Receiver User's Tips

- If the satellite signals can not be locked or experiencing receiving problem (while in urban area), following steps are suggested:
 - a) Please plug the external active antenna into GPS receiver and put the antenna outdoor or on the roof of the vehicle for better receiving performance.
 - b) Move to another open space or reposition GPS receiver toward the direction with least blockage.
 - c) Move the GPS receiver away from the interference sources.
 - d) Wait until the weather condition is improved.
- Some vehicles having heavy metallic sun protecting coating on windshields may affect signal receptions
- Driving in and around high buildings may affect signal reception.
- Driving under tunnels or in buildings may affect signal reception.
- In general, GPS receiver performs best in open space where it can see clean sky. Weather will affect GPS reception – rain & snow contribute to worsen sensitivity.
- When GPS receiver is moving, it will take longer time to get position fix. Wait for satellite signals to be locked at a fixed point when first power-on the GPS receiver to ensure quick GPS position fix.

4.4 IR reflow profile

Ramp-down rate : 6 °C /sec. max.
 Time 25 °C to peak temperature : 8 minutes max.
 Cycle interval : 5 minus



4.5 How to avoid ESD damage to ICs

- Any person handling the ICs should be grounded either with a wrist strap or ESD-protective footwear used in conjunction with a conductive or static-dissipative floor or floor mat.
- The work surface where devices are placed for handling, processing, testing, etc., must, be made of static-dissipative material and be grounded to ESD ground.
- All insulator materials must either be removed from the work area or must be neutralized with an ionizer. Static-generating clothing must be covered with an ESD-protective smock.
- When ICs are being stored, transferred between operations or workstations, or shipped, they must be kept in a Faraday shield container with inside surfaces (surfaces touching the ICs) that are static-dissipative.

Contact Information

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