GPS Engine Board

EB-550

EB-550 is a complete GPS engine with antenna in miniature 43 x 9 x 4 mm dimension. It provides great navigation performance under dynamic conditions in areas with limited sky view like urban canyons. High sensitivity up to **-165dBm*** for weak signal operation without compromising accuracy. EB-550 brings the best GPS reception with compact size for all kinds of embedded applications.

Key Features :

- Small form factor: 43 x 9 x 2.4 mm
- High sensitivity -165dBm*
- Tracks 66-Channel of satellites
- Fast Position Fix
- Low power consumption
- Integrate GPS antenna
- Support off line AGPS.
- Lead-Free RoHS/WEEE compliant

PIN Definition :

Pin #	Name	Pin #	Name
1	GND	9	GND
2	GND	10	GND
3	GND	11	RXA
4	GND	12	TXA
5	GND	13	CTRL
6	GND	14	Vcc
7	GND	15	GND
8	GND	16	GND



Applications :

- Handheld devices
- Automotive and Marine Navigation
- Emergency Locator
- Geographic Surveying
- Personal Positioning
- Sporting and Recreation
- Embedded applications



* Refer to chip specifications

TRANSYSTEM INC.

An A+ Supplier of Microwave communication & GPS products



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Revision History

Rev.	Date	Description	
0.1	12-20-2010	Initial draft	
0.2	03-07-2011	Add Molex connector P/N	
0.3	04-06-2011	Modify the pin location of the dimensional drawing	
	MM-DD-YYYY		





EB-550 is ESD (electrostatic discharge) sensitive device and may be damaged with ESD or spike voltage. Please handle with care to avoid permanent malfunction or performance degradation.

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1 Introduction

EB-550 is a complete GPS engine solution with integrated chip antenna in a miniature 43 x 9 x 2.4 mm dimension. The form factor best fit for board edge system configuration to minimize overall system size. It provides great GPS reception performance under dynamic conditions in areas with limited sky view like urban canyons. Its high sensitivity is the best for weak signal operation without compromising accuracy. EB-550 brings the best GPS reception with high integration in compact size for all kinds of embedded applications.

- 1.1 Key Features
 - Small form factor: 43 x 9 x 2.4 mm
 - High sensitivity -165dBm*
 - Tracks 66-Channel of satellites
 - Fast Position Fix
 - Low power consumption
 - Integrate GPS antenna
 - Support off line AGPS.
 - Lead-Free RoHS/WEEE compliant
- 1.2 Applications
 - Handheld devices
 - Automotive and Marine Navigation
 - Emergency Locator
 - Geographic Surveying
 - Personal Positioning
 - Sporting and Recreation
 - Embedded applications
- 1.3 Labeling

There are 4 fields of top marking on the GPS engine and they are :

EB-550 tsi YYWW NNNNN

- Area #1: TSI company icon
- Area #2: Model number, i.e. EB-550
- Area #3: Date code (YYWW), the year and week when the product is built.
- Area #4: Lot control code for TSI internal use



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2 Technical Description

2.1 Block Diagram





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EB-550 Data Sheet

2.2 Pin Definition

Pin#	Name	Туре	Description	
1	GND	Р	Power ground	
2	GND	Р	Power ground	
3	GND	Р	Power ground	
4	GND	Р	Power ground	
5	GND	Р	Power ground	
6	GND	Р	Power ground	
7	GND	Р	Power ground	
8	GND	Р	Power ground	
9	GND	Р	Power ground	1
10	GND	Р	Power ground	
11	RX0	I	GPS RX0, input to EB-550	
12	TX0	0	GPS TX0, output from EB-550	
13	CTRL	I	GPS enable, open if not used	
14	Vcc	Р	Power input, 3.0~4.2Vdc	
15	GND	Р	Power ground	
16	GND	Р	Power ground	
P: Po	wer I: In	put O:	Output	

2.3 General Comment

Following comments should be considered for a design using EB-550 module:

• Serial port default configuration: 115,200 baud, 8 data bits, no parity, 1 stop bit, no flow control





2.4 Specifications

Item	Description	
General	L1 frequency, C/A code (SPS) 66 independent tracking channels	
Sensitivity*	-165dBm /Tracking; -148dBm /Acquisition	
Update Rate	Up to 10Hz	
Accuracy	<3m CEP (50%) without SA 2.5m DGPS (WAAS, EGNOS, MSAS, RTCM)	
Acquisition (open sky)	Cold Start: 35sec Warm Start: 34sec Hot Start: 1.5sec	
Reacquisition	< 1sec	
Dynamics	Altitude: 18000m (max.) Velocity: 515m/sec (max.) Vibration: 4G (max.)	
NMEA	NMEA0183 v3.1 GGA, GSA, GSV, RMC (Default) / GLL, VTG (Optional)	
Datum	Default WGS-84	
Antenna	Build-in chip antenna	
Power Supply	DC 3.0V ~ 4.2V	
Current	30mA @ 3.3V / Tracking	
Interface	UART, Baud rate : 4800/9600(Default)//115200	
Mounting	Molex 16 pin male (52465-1629) board to board connector	
Dimension	43 x 9 x 2.4 (H, include shielding box) mm	
Operating Temp.	-30°C to 85°C	
Storage Temp.	-40°C to 85°C	
Operating Humidity	\leq 95%, non condensing	



3 Electrical Characteristics

3.1 Absolute maximum ratings

Symbol	Parameter	Min	Max	Unit
Vcc	power supply	-0.3	+4.2	V
Vin	voltage to any pin	-0.3	+3.6	V
lov	input current on any pin	-10	10	mA
ltdv	absolute sum of all input currents during overload condition		200	mA
Tst	storage temperature	-40	85	C

Table 5: Absolute maximum ratings

Note:

- (1) Stresses beyond absolute maximum ratings may cause permanent damage to the device.
- (2) Exposure to absolute maximum rating conditions for extended period may affect device reliability.

3.2 Operating Conditions

Pin	Description		Typical	Max
	Vcc	3.0V	3.3V	4.2V
14	Peak Acquisition Current (1)			30mA
	Tracking Current (2)		23mA	

Table 6: Electrical characteristics

Note:

- (1) Peak acquisition current is the maximum current with passive antenna.
- (2) Tracking current is the average current with passive antenna includes tracking and post acquisition portion.

3.3 DC Electrical Characteristics

Symbol	Parameter	Min	Max	Unit
	Voh	2.4	3.9	V
	Vol	-0.3	0.4	V
	Vih	2.0	3.6	V
	Vil	-0.3	0.8	V



4 Serial Port Interface

EB-550 provides 2- wire digital UART port for communication of GPS position data using NMEA protocol or MTK extension protocol. UART port is capable of 4800 to 115200 baud rate.

4.1 Protocol

EB-550 is default to support standard NMEA-0183 protocol. In addition, a series of MTK extensions (PMTK messages) have been developed that can be used to provide extended capabilities common to many applications. Please refer to "GPS Engine Board UART Port Command" for detailed command information.

4.2 NMEA Protocol

EB-550 is capable of supporting following NMEA formats:

NMEA Prefix	Format	Direction
\$GPGGA	GPS fix data	Out
\$GPGLL	Geographic position Latitude / Longitude	Out
\$GPGSA	GNSS DOP and active satellites	Out
\$GPGSV	Satellites in view	Out
\$GPRMC	Recommended minimum specific GNSS data	Out
\$GPVTG	Velocity and track over ground	Out
\$GPZDA	Date and time	Out



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5 Dimension and Package

5.1 Mechanical Dimension



5.2 Packing

EB-550 comes in sealed individual package to provide maximum protection to the module against moisture and ESD during storage and shipment.



6 Application Information

6.1 Minimum Configuration



Note : 1) Keep EB-550 top side away from metal parts and RF transmitter to avoid interference of GPS signal reception.

2) Provide good grounding to the connector interface as well as the two square contacts on the bottom side of EB-550.

- 3) Use of noise-free power source to supply VCC to EB-550.
- 4) Keep at least 1mm spacing from all directions of the GPS chip antenna.

6.2 General GPS Receiver User's Tips

In general, GPS receiver performs best in open space where it can see clean sky. Weather condition will affect GPS reception – rain & snow contribute to worsen sensitivity.

If the satellite signals can not be locked or experiencing receiving problem (while in urban area), following steps are suggested:

- Use of external active antenna if that option exists.
- Move to another open space or reposition GPS receiver toward the direction with least blockage.
- Move the GPS receiver away from the interference sources.
- Wait until the weather condition is improved.

Some vehicles using heavy metallic sun protecting coating on windshields may affect GPS signal reception.

- Driving in and around high buildings may affect signal reception.
- Driving in tunnels or in building structure may affect signal reception.
- When GPS receiver is moving, it will take longer time to get position fix. Wait for satellite signals to be locked at a fixed point when first power-on the GPS receiver to ensure quick GPS position fix.



7 Quality and Reliability

Each module is electrically tested prior to packing and shipping to ensure state of the art product quality and best GPS receiver performance and accuracy.

7.1 Environmental Conditions

Operating temperature	-30 ~ +85 <i>°</i> C
Operating humidity	Max. 95%, non-condensing
MSL JEDEC (Moisture Sensitivity Level)	3
Storage temperature	-40 ~ +85 <i>°</i> C
Storage	12 months in original package.

7.2 How to avoid ESD damage

- Any person handling the module should be grounded either with a wrist strap or ESD-protective footwear used in conjunction with a conductive or static-dissipative floor or floor mat.
- The work surface where devices are placed for handling, processing, testing, etc., must, be made of static-dissipative material and be grounded to ESD ground.
- All insulator materials must either be removed from the work area or must be neutralized with an ionizer. Static-generating clothing must be covered with an ESD-protective smock.
- When module are being stored, transferred between operations or workstations, or shipped, they must be kept in a Faraday shield container with inside surfaces (surfaces touching the module) that are static-dissipative.



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