





## **APPLICABILITY TABLE**

PRODUCT	P/N
GE864-QUAD	GE864QUD00xxxxx
GC864-QUAD	GC864QUD00xxxxx
GC864-QUAD with SIM holder	GC864QUH00xxxxx



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## 1. Introduction

## 1.1. Scope

The aim of this document is the description of some hardware solutions useful for developing a product with the Telit GE/GC864-QUAD modules.

## 1.2. Audience

This document is intended for Telit customers, who are integrators, about to implement their applications using our GE/GC864-QUAD modules.

## 1.3. Contact Information, Support

For general contact, technical support, to report documentation errors and to order manuals, contact Telit's Technical Support Center (TTSC) at:

TS-EMEA@telit.com

TS-NORTHAMERICA@telit.com

TS-LATINAMERICA@telit.com

TS-APAC@telit.com

#### Alternatively, use:

http://www.telit.com/en/products/technical-support-center/contact.php

For detailed information about where you can buy the Telit modules or for recommendations on accessories and components visit:

#### http://www.telit.com

To register for product news and announcements or for product questions contact Telit's Technical Support Center (TTSC).

Our aim is to make this guide as helpful as possible. Keep us informed of your comments and suggestions for improvements.

Telit appreciates feedback from the users of our information.



## 1.4. Document Organization

This document contains the following chapters:

<u>Chapter 1: "Introduction"</u> provides a scope for this document, target audience, contact and support information, and text conventions.

<u>Chapter 2: "Overview"</u> provides an overview of the document.

Chapter 3: "Mechanical Dimensions"

<u>Chapter 4: "Electrical Connections"</u> deals with the pin out configuration and layout.

<u>Chapter 5: "Hardware Commands"</u> How to operate on the modules via hardware.

<u>Chapter 6: "Power supply"</u> Power supply requirements and general design rules.

<u>Chapter 7: "Antenna"</u> The antenna connection and board layout design are the most important parts in the full product design.

<u>Chapter 8: "Logic Level specifications"</u> Specific values adopted in the implementation of logic levels for the modules.

<u>Chapter 9: "Serial ports"</u> The serial port on the modules is the core of the interface between the modules and OEM hardware

<u>Chapter 10: "Audio Section overview"</u> Refers to the audio blocks of the Base Band Chip of the modules.

<u>Chapter 11: "General Purpose I/O"</u> How the general purpose I/O pads can be configured.

Chapter 12 "DAC and ADC Section" Deals with these two kind of converters.

Chapter 13: "Mounting the GE/GC864 QUAD on the application board"
Recommendations and specifics on how to mount the modules on the user's board.



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## 1.5. Text Conventions



<u>Danger – This information MUST be followed or catastrophic equipment failure or bodily injury may occur.</u>



Caution or Warning — Alerts the user to important points about integrating the module, if these points are not followed, the module and end user equipment may fail or malfunction.



Tip or Information – Provides advice and suggestions that may be useful when integrating the module.

All dates are in ISO 8601 format, i.e. YYYY-MM-DD.

## 1.6. Related Documents

- Telit Modules Software User Guide, 1vv0300784
- Audio settings application note, 80000NT10007a
- Digital voice Interface Application Note, 80000NT10004a
- GE864 and GC864 Product description, 80273ST10008a
- SIM Holder Design Guides, 80000NT10001a
- AT Commands Reference Guide, 80000ST10025a



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## 1.7. Document History

Revision	Date	Changes
ISSUE#0	2010-12-23	Release First ISSUE# 0



## 2. Overview

In this document all the basic functions of a mobile phone will be taken into account; for each one of them a proper hardware solution will be suggested and eventually the wrong solutions and common errors to be avoided will be evidenced. Obviously this document cannot embrace the whole hardware solutions and products that may be designed. The wrong solutions to be avoided shall be considered as mandatory, while the suggested hardware configurations shall not be considered mandatory, instead the information given shall be used as a guide and a starting point for properly developing your product with the Telit GE864-QUAD and GC864-QUAD cellular modules. For further hardware details that may not be explained in this document refer to the Telit GE864-QUAD and GC864-QUAD Product Description document where all the hardware information is reported.



#### NOTICE:

The integration of the GE864-QUAD and GC864-QUAD cellular modules within user application shall be done according to the design rules described in this manual.

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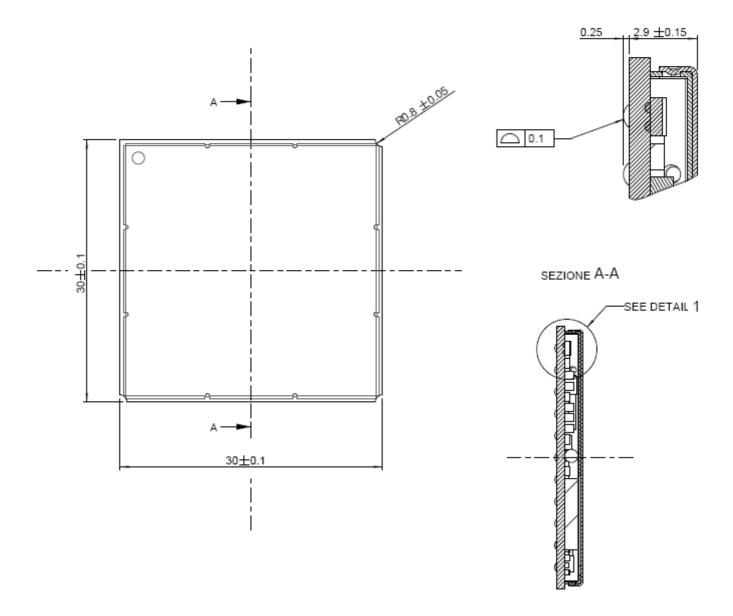
## 3. Mechanical Dimensions

## 3.1. GE864 QUAD

The Telit GE864 module overall dimensions are:

Length: 30 mmWidth: 30 mmThickness: 2.9 mm

DETAIL 1 SCALE 8:1



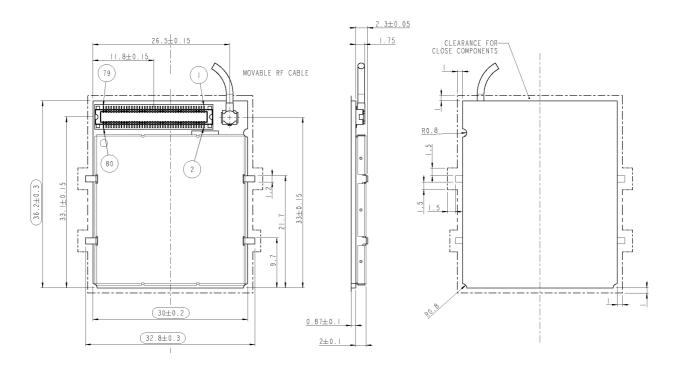


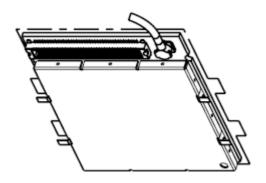
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## 3.2. GC864 QUAD

The Telit GC864-QUAD module overall dimensions are:

Length: 36.2 mm
 Width: 30 mm
 Thickness: 3.2 mm







## 4. Electrical Connections

## 4.1. GE864 QUAD

## 4.1.1. PIN-OUT

Ball	Signal	1/0	Function	Туре			
Audio	•				•		
Н9	EAR_MT-	A0	Handset earphone signal output, phase -	Handset earphone signal output, phase -			
G10	EAR_MT+	A0	Handset earphone signal output, phase +		Audio		
H10	EAR_HF+	A0	Handsfree ear output, phase +		Audio		
J10	EAR_HF-	A0	Handsfree ear output, phase -		Audio		
J8	MIC_MT+	Al	Handset mic.signal input; phase+		Audio		
G9	MIC_MT-	Al	Handset mic.signal input; phase-		Audio		
G8	MIC_HF+	Al	Handsfree mic. input; phase +		Audio		
J9	MIC_HF-	Al	Handsfree mic.input; phase -		Audio		
F9	AXE	1	Handsfree switching	100K	CMOS 2.8V		
SIM ca	ard interface						
C10	SIMCLK	0	External SIM signal – Clock		1,8 / 3V		
E9	SIMRST	0	External SIM signal – Reset		1,8 / 3V		
D10	SIMIO	1/0	External SIM signal – Data I/O		1,8 / 3V		
C11	SIMIN	1	External SIM signal – Presence (active low)	47K	1,8 / 3V		
D4 <sup>1</sup>	SIMVCC	-	External SIM signal – Power supply for the SIM 1		1,8 / 3V		
Trace							
D11	TX_TRACE	0	TX Data for debug monitor / DVI1_CLK (Digital Voice Interface)		CMOS 2.8V		
F10	RX_TRACE	I	RX Data for debug monitor / DVI1_WA (Digital Voice Interface)	RX Data for debug monitor / DVI1_WA (Digital Voice Interface)			
Prog.	/ Data + HW Flow Cont	rol					
E7	C103/TXD	1	Serial data input (TXD) from DTE		CMOS 2.8V		
Н8	C104/RXD	0	Serial data output to DTE		CMOS 2.8V		
B7	C108/DTR	1	Input for Data terminal ready signal (DTR) from DTE		CMOS 2.8V		
F7	C105/RTS	1	Input for Request to send signal (RTS) from DTE		CMOS 2.8V		
F6	C106/CTS	0	Output for Clear to send signal (CTS) to DTE		CMOS 2.8V		
D9	C109/DCD	0	Output for Data carrier detect signal (DCD) to DTE	CMOS 2.8V			
E11	C107/DSR	0	Output for Data set ready signal (DSR) to DTE / DVI1_RX (Digital Voice Interface)	' I I I I I I I I I I I I I I I I I I I			
B6	C125/RING	0	Output for Ring indicator signal (RI) to DTE		CMOS 2.8V		
DAC a	nd ADC						
C7	DAC_OUT	AO	Digital/Analog converter output		D/A		
J11	ADC_IN1	Al	Analog/Digital converter input		A/D		

 $<sup>^{\</sup>rm 1}$  On this line a maximum of 10nF bypass capacitor is allowed





Ball	Signal	1/0	Function	Туре				
H11	ADC_IN2	Al	Analog/Digital converter input	Analog/Digital converter input				
G11	ADC_IN3	Al	Analog/Digital converter input A/D					
Misce	llaneous Functions							
A2	RESET*	1	Reset input	eset input				
E2	VRTC	AO	VRTC Backup capacitor		Power			
D8	STAT_LED	0	Status indicator led		CMOS 1.8V			
G1	CHARGE	Al	Charger input		Power			
G2	CHARGE	Al	Charger input		Power			
J5	ON_OFF*	1	Input command for switching power ON or OFF (toggle command).	47K	Pull up to VBATT			
D5	VAUX1	-	Power output for external accessories		-			
L8	PWRMON	0	Power ON Monitor		CMOS 2.8V			
L4	Antenna	0	Antenna output – 50 ohm		RF			
D7	DVI2_CLK	-	DVI2_CLK (Digital Voice Interface)	4.7K	CMOS 2.8			
C6	DVI1_TX	-	Digital Transmitting Data	4.7K	CMOS 2.8			
GPI0								
G4	TGPIO_12	1/0	Telit GPI012 Configurable GPI0		CMOS 2.8V			
C2	TGPIO_03	1/0	Telit GPI003 Configurable GPI0		CMOS 2.8V			
В3	TGPIO_04	1/0	Telit GPI004 Configurable GPI0 / RF Transmission Control	· ·				
C3	TGPI0_20	1/0	Telit GPI020 Configurable GPI0		CMOS 2.8V			
B4	TGPI0_14	1/0	Telit GPI014 Configurable GPI0		CMOS 2.8V			
D1	TGPIO_11	1/0	Telit GPI011 Configurable GPI0		CMOS 2.8V			
B1	TGPIO_19	1/0	Telit GPI019 Configurable GPI0		CMOS 2.8V			
C1	TGPIO_01	1/0	Telit GPI001 Configurable GPI0		CMOS 2.8V			
K7	TGPI0_18	1/0	Telit GPI018 Configurable GPI0/ DVI2_RX [Digital Voice Interface]		CMOS 2.8V			
H5	TGPI0_17	1/0	Telit GPI017 Configurable GPI0 / DVI2_WA [Digital Voice Interface]		CMOS 2.8V			
F5	TGPIO_15	1/0	Telit GPI015 Configurable GPI0		CMOS 2.8V			
K11	TGPIO_08	1/0	Telit GPI008 Configurable GPI0		CMOS 2.8V			
B5	TGPIO_06 / ALARM	1/0	Telit GPI006 Configurable GPI0 / ALARM		CMOS 2.8V			
C9	TGPIO_09	1/0	Telit GPI009 GPI0 I/O pin		CMOS 2.8V			
E6	TGPIO_02 / JDR	1/0	Telit GPI002 I/O pin / Jammer detect report		CMOS 2.8V			
L9	TGPIO_07 / BUZZER	1/0	Telit GPI007 Configurable GPI0 / Buzzer		CMOS 2.8V			
H6	TGPIO_16	1/0	Telit GPI016 Configurable GPI0		CMOS 2.8V			
K10	TGPIO_13	1/0	Telit GPI013 Configurable GPI0		CMOS 2.8V			
K8	TGPIO_05 / RFTXMON	I/O	ON monitor	Telit GPI005 Configurable GPI0 / Transmitter ON monitor				
L10	TGPIO_21	1/0	Telit GPI021 Configurable GPI0	-				
E8	TGPI0_22	1/0	Telit GPI022 Configurable GPI0	اا				
H3	TGPIO_10	I/O	Telit GPI010 Configurable GPI0 / DVI2_TX [Digital Voice Interface]		CMOS 2.8V			
	r Supply							
J1	VBATT	-	Main power supply		Power			





Ball	Signal	1/0	Function Internal PULL UP Type		Туре	
K1	VBATT	-	Main power supply		Power	
J2	VBATT	-	Main power supply		Power	
K2	VBATT	-	Main power supply		Power	
A1	GND	-	Ground		Power	
F1	GND	-	Ground		Power	
H1	GND	-	Ground		Power	
L1	GND	-	Ground		Power	
H2	GND	-	Ground		Power	
L2	GND	-	Ground		Power	
J3	GND	-	Ground		Power	
K3	GND	-	Ground		Power	
L3	GND	-	Ground		Power	
K4	GND	-	Ground		Power	
K5	GND	-	Ground		Power	
D6	GND	-	Ground		Power	
K6	GND	-	Ground		Power	
L6	GND	-	Ground		Power	
A11	GND	-	Ground		Power	
F11	GND	-	Ground		Power	
L11	GND	-	Ground		Power	
RESEF	RVED					
A10		-				
А3		-				
A4		-				
A5		-				
A6		-				
Α7		-				
A8		-				
Α9		-				
B10		-				
B11		-				
B2		-				
B8		-				
В9		-				
C4		-				
C8		-				
D2		-				
D3		-				
E1		-				
E10		-				
E3		-				
E4		-				
F2		-				
F3		-				



Ball	Signal	1/0	Function	Internal PULL UP	Туре
F4		-			
G6		-			
G7		-			
H4		-			
H7		-			
J4		-			
J6		-			
J7		-			
K9		-			
L5		-			
E5		-			
L7		-			
G5		-			
G3		-			
F8		-			
C5		-			



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#### NOTE:

The GE864-QUAD has two DVI ports on the system interface.

Only one port can be selected and be active at the time. The choice of DVI port depends on the needs of the application.

For master mode Telit suggests that applications only use the DVI2 port as this minimizes the impact on the module functionality.

#### NOTE:

RESERVED pins must not be connected

#### NOTE:

If not used, almost all pins must be left disconnected. The only exceptions are the following pins<sup>2</sup>:

pin	signal
J1,K1,J2,K2	VBATT
A1,F1,H1,L1,H2,L2,J3,K3,L3,	GND
K4,K5,D6,K6,L6,A11,F11,L11	
J5	ON/OFF*
E7	TXD
A2	RESET*
H8	RXD
F7	RTS

<sup>&</sup>lt;sup>2</sup> RTS should be connected to the GND (on the module side) if flow control is not used.





## 4.1.2. BGA Balls Layout

## Top view

	A	В	С	D	E	F	G	Н	J	К	L
1	GND	TGPI0_19	TGPI0_01	TGPI0_11	-	GND	CHARGE	GND	VBATT	VBATT	GND
2	RESET*	-	TGPI0_03	-	VRTC	-	CHARGE	GND	VBATT	VBATT	GND
3	-	TGPIO_04	TGPIO_20	ı	-	ı	-	TGPI0_10	GND	GND	GND
4	-	TGPIO_14	-	SIMVCC	-	-	TGPIO_12	-	-	GND	Antenna
5	-	TGPIO_06 / ALARM		VAUX1	-	TGPIO_15	-	TGPIO_17	ON_OFF*	GND	-
6	-	C125/RING		GND	TGPIO_02/ JDR	C106 / CTS	-	TGPI0_16	-	GND	GND
7	-	C108 / DTR	DAC_OUT	DVI2_CLK	C103 / TXD	C105 / RTS	-	-	-	TGPIO_18	-
8	-	-	-	STAD_LED	TGPIO_22	-	MIC_HF+	C104 / RXD	MIC_MT+	TGPIO_05 / RFTXMON	PWRMON
9	-	-	TGPIO_09	C109 / DCD	SIMRST	AXE	MIC_MT-	EAR_MT-	MIC_HF-	-	TGPIO_07 / BUZZER
10	-	-	SIMCLK	SIMIO	1	RX_TRACE	EAR_MT+	EAR_HF+	EAR_HF-	TGPIO_13	TGPIO_21
11	GND	-	SIMIN	TX_TRACE	C107 / DSR	GND	ADC_IN3	ADC_IN2	ADC_IN1	TGPI0_08	GND



AUDIO Signals balls
SIM CARD interface balls
TRACE Signals balls
Prog. / data + Hw Flow Control signals balls
DAC and ADC signals balls
MISCELLANEOUS functions signals balls
TELIT GPIO balls
POWER SUPPLY VBATT balls
POWER SUPPLY GND balls
RESERVED



## 4.2. GC864-QUAD

## 4.2.1. PIN-OUT

The GC864-QUAD uses a 80 pin Molex p.n. 53949-0878 male connector for the connections with the external applications. This connector matches the 54150-0878 models.

Pin	Signal	1/0	Function	Internal Pull up	Туре	
Power	Power Supply					
1	VBATT	-	ain power supply		Power	
2	VBATT	-	Main power supply		Power	
3	VBATT	-	Main power supply		Power	
4	VBATT	-	Main power supply		Power	
5	GND	-	Ground		Power	
6	GND	-	Ground		Power	
7	GND	-	Ground	ound Pc		
Audio	•	<u> </u>				
8	AXE	I	Handsfree switching	100KΩ	CMOS 2.8V	
9	EAR_HF+	A0	Handsfree ear output, phase +		Audio	
10	EAR_HF-	AO	Handsfree ear output, phase -		Audio	
11	EAR_MT+	AO	Handset earphone signal output, phase +		Audio	
12	EAR_MT-	AO	Handset earphone signal output, phase -		Audio	
13	MIC_HF+	AI	Handsfree microphone input; phase		Audio	
14	MIC_HF-	AI	Handsfree microphone input; phase		Audio	
15	MIC_MT+	AI	Handset microphone signal input; phase+		Audio	
16	MIC_MT-	AI	Handset microphone signal input; phase-		Audio	
SIM C	ard Interface					
18³	SIMVCC	-	External SIM signal – Power supply for the SIM		1.8 / 3V	
19	SIMRST	0	External SIM signal – Reset		1.8 / 3V	
20	SIMI0	1/0	External SIM signal - Data I/O		1.8 / 3V	
21	SIMIN	I	External SIM signal - Presence (active low)	47KΩ	1.8 / 3V	
22	SIMCLK	0	External SIM signal – Clock	ixternal SIM signal – Clock		
Trace						
23	RX_TRACE	I	RX Data for debug monitor/ DVI1_WA (Digital Voice Interface)		CMOS 2.8V	
24	TX_TRACE	0	TX Data for debug monitor/ DVI1_CLK (Digital Voice Interface)		CMOS 2.8V	
Prog.	Prog. / Data + Hw Flow Control					
25	C103/TXD	I	Serial data input (TXD) from DTE		CMOS 2.8V	

 $<sup>^{\</sup>rm 3}$  On this line a maximum of 10nF bypass capacitor is allowed





Pin	Signal	1/0	Function	Internal Pull up	Туре
26	C104/RXD	0	Serial data output to DTE	,	CMOS 2.8V
27	C107/DSR	0	utput for Data set ready signal (DSR) to DTE/ DVI1_RX (Digital Voice terface)		CMOS 2.8V
28	C106/CTS	0	Output for Clear to send signal (CTS) to DTE		CM0S 2.8V
29	C108/DTR	ı	Input for Data terminal ready signal (DTR) from DTE		CMOS 2.8V
30	C125/RING	0	Output for Ring indicator signal (RI) to DTE		CM0S 2.8V
31	C105/RTS	ı	Input for Request to send signal (RTS) from DTE		CMOS 2.8V
32	C109/DCD	0	Output for Data carrier detect signal (DCD) to DTE		CM0S 2.8V
DAC a	and ADC				
37	ADC_IN1	Al	Analog/Digital converter input		A/D
38	ADC_IN2	Al	Analog/Digital converter input		A/D
39	ADC_IN3	Al	Analog/Digital converter input		A/D
40	DAC_OUT	AO	Digital/Analog converter output		D/A
Misce	llaneous Functions				
45	STAT_LED	0	Status indicator led		CMOS 1.8V
46	GND	-	Ground		Ground
49	PWRMON	0	Power ON Monitor		CMOS 2.8V
50	VAUX1	-	Power output for external accessories		-
51	CHARGE	Al	Charger input		Power
52	CHARGE	Al	Charger input		Power
53	ON/OFF*	ı	nput command for switching power ON or OFF (toggle command). The ulse to be sent to the GC864-QUAD must be equal or greater than 1 econd. 47K $\Omega$		Pull up to VBATT
54	RESET*	ı	Reset input		
55	VRTC	AO	RTC Backup capacitor		Power
36	DVI2_CLK	-	Digital Voice Interface Clock	4.7KΩ	CM0S 2.8V
Telit (	PIO				
56	TGPIO_19	1/0	Telit GPI019 Configurable GPI0		CMOS 2.8V
57	TGPIO_11	I/O	Telit GPI011 Configurable GPI0		CMOS 2.8V
58	TGPI0_20	I/O	Telit GPI020 Configurable GPI0		CMOS 2.8V
59	TGPIO_04	I/O	Telit GPI04 Configurable GPI0 / RF Transmission Control		CMOS 2.8V
60	TGPIO_14	1/0	Telit GPI014 Configurable GPI0		CMOS 2.8V
61	TGPIO_15	1/0	Telit GPI015 Configurable GPI0		CMOS 2.8V
62	TGPIO_12	1/0	Telit GPI012 Configurable GPI0		CMOS 2.8V
63	TGPIO_10	I/O	Telit GPI010 Configurable GPI0 / DVI2_TX (Digital Voice Interface)		CMOS 2.8V
64	TGPI0_22	1/0	Telit GPI022 Configurable GPI0		CM0S 1.8V
65	TGPIO_18	I/O	Telit GPI018 Configurable GPI0 / DVI2_RX (Digital Voice Interface)		CMOS 2.8V
66	TGPI0_03	I/O	Telit GPI03 Configurable GPI0		CMOS 2.8V
67	TGPI0_08	I/O	Telit GPI08 Configurable GPI0		CM0S 2.8V
68	TGPIO_06 / ALARM				CMOS 2.8V





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Pin	Signal	1/0	Function	Internal Pull up	Туре	
70	TGPIO_01	1/0	elit GPI01 Configurable GPI0		CMOS 2.8V	
71	TGPIO_17	1/0	Telit GPI017 Configurable GPI0 / DVI2_WA (Digital Voice Interface)		CMOS 2.8V	
72	TGPIO_21	1/0	Telit GPI021 Configurable GPI0		CMOS 2.8V	
73	TGPIO_07 / BUZZER	1/0	Telit GPI07 Configurable GPI0 / Buzzer		CMOS 2.8V	
74	TGPI0_02 / JDR	1/0	Telit GPI002 I/O pin / Jammer detect report		CMOS 2.8V	
75	TGPIO_16	1/0	Telit GPI016 Configurable GPI0		CMOS 2.8V	
76	TGPI0_09	1/0	Telit GPI09 Configurable GPI0		CMOS 2.8V	
77	TGPIO_13	1/0	Telit GPI013 Configurable GPI0		CMOS 2.8V	
78	TGPIO_05/ RFTXMON	1/0	Telit GPI005 Configurable GPI0 / Transmitter 0N monitor		CMOS 2.8V	
RESE	RESERVED					
17		-				
33		-				
34		-				
41		-				
42		-				
43		-				
44		-				
47		-				
48		-				
79		-				
69		-				
80		-				
35	DVI1_TX	-	Digital Voice Interface Transmitted Data	4.7KΩ	CMOS 2.8V	



#### NOTE:

The GC864 has two DVI ports on the system interface.

Only one port can be selected and be active at the time. The choice of DVI port depends on the needs of the application, but Telit suggests that applications only use the DVI2 port as this minimizes the impact on the module functionality.





#### NOTE:

Reserved pins must not be connected.

#### NOTE:

RTS must be connected to the GND (on the module side) if flow control is not used.



#### NOTE:

If not used, almost all pins must be left disconnected. The only exceptions are the following pins<sup>4</sup>:

Pin	Signal	Function
1	VBATT	Main power supply
2	VBATT	Main power supply
3	VBATT	Main power supply
4	VBATT	Main power supply
5	GND	Ground
6	GND	Ground
7	GND	Ground
46	GND	Ground
25	C103/TXD	Serial data input (TXD) from DTE
26	C104/RXD	Serial data output to DTE
31	C105/RTS	Input for Request to send signal (RTS) from DTE
53	ON/OFF*	Input command for switching power ON or OFF (toggle command).
54	RESET*	Reset input

#### 4.2.2. Antenna Connector

The GC864-QUAD module is equipped with a 50  $\Omega$  RF connector from Murata, GSC type P/N MM9329-2700B.

The counterpart suitable is Murata MXTK92 Type or MXTK88 Type.

Moreover, the GC864-QUAD has the antenna pads on the back side of the PCB. This allows the manual soldering of the coaxial cable directly on the back side of the PCB. However, the soldering is not an advisable solution for a reliable connection of the antenna.

<sup>&</sup>lt;sup>4</sup> RTS should be connected to the GND (on the module side) if flow control is not used.





## 5. Hardware Commands

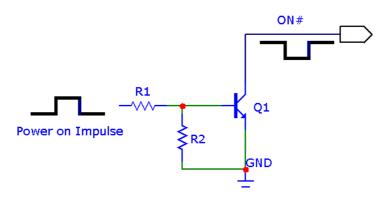
## 5.1. Turning ON the GE/GC864-QUAD

To turn on the GE/GC864-QUAD the pad ON# must be tied low for at least 1 second and then released.

When the power supply voltage is lower than 3.4V the pad ON# must be tied low for at least 4 seconds.

The maximum current that can be drained from the ON# pad is 0,1 mA.

A simple circuit to do it is:





#### NOTE:

Do not use any pull up resistor on the ON# line, it is internally pulled up. Using pull up resistor may bring to latch up problems on the GE/GC864-QUAD power regulator and improper power on/off of the module. The line ON# must be connected only in open collector configuration.

#### NOTE:

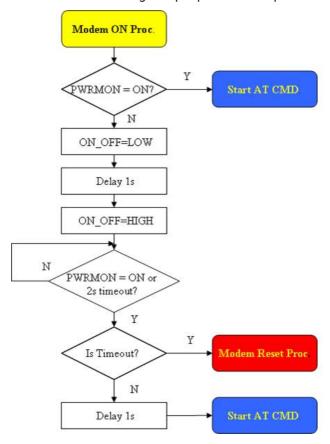
In this document all the lines that are inverted, hence have active low signals are labeled with a name that ends with a "#" or with a bar over the name.

#### NOTE:

The GE/GC864-QUAD turns fully on also by supplying power to the Charge pad (Module provided with a battery on the VBATT pads).



A flow chart showing the proper turn on procedure is displayed below:





#### TIP:

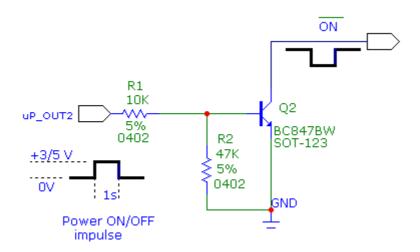
To check if the device has powered on, the hardware line PWRMON must be monitored. After 900ms the line raised up the device could be considered powered on.

PWRMON line rises up also when supplying power to the Charge pad



For example:

Let us assume you need to drive the ON# pad with a totem pole output of a +3/5 V micro controller (uP\_OUT1):



Let us assume you need to drive the ON# pad directly with an ON/OFF button:

## 5.2. Turning OFF the GE/GC864-QUAD

The turning off of the device can be done in two ways:

- via AT command (see Telit Modules Software User Guide)
- by tying low pin ON#

Either ways, when the device issues a detach request to the network informing that the device will not be reachable any more.

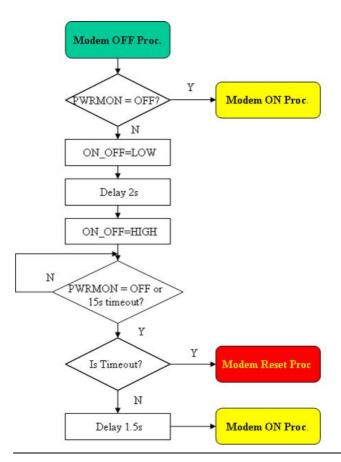
To turn OFF the GE/GC864-QUAD the pad ON# must be tied low for at least 2 seconds and then released.

The same circuitry and timing for the power on shall be used.

The device shuts down after the release of the ON# pad.









#### TIP:

To check if the device has powered off, the hardware line PWRMON must be monitored. When PWRMON goes low, the device has powered off.

### 5.2.1. Hardware Unconditional Restart



#### **WARNING:**

The hardware unconditional Restart must not be used during normal operation of the device since it does not detach the device from the network. It shall be kept as an emergency exit procedure to be done in the rare case that the device gets stacked waiting for some network or SIM responses.

To unconditionally restart the GE/GC864-QUAD, the pad RESET# must be tied low for at least 200 milliseconds and then released.

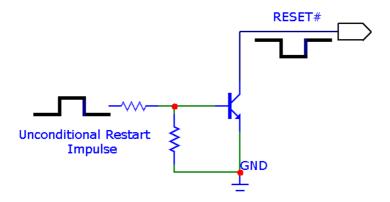
The maximum current that can be drained from the ON# pad is 0.15 mA.





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A simple circuit to do it is:





#### NOTE:

Do not use any pull up resistor on the RESET# line nor any totem pole digital output. Using pull up resistor may bring to latch up problems on the GE/GC864-QUAD power regulator and improper functioning of the module. The line RESET# must be connected only in open collector configuration.

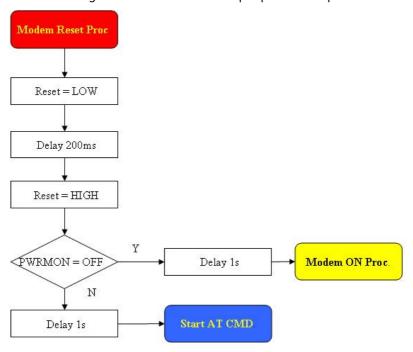


#### TIP:

The unconditional hardware Restart must always be implemented on the boards and must be used by the software as an emergency exit procedure.

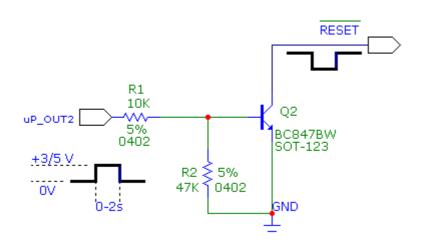


The following flow chart shows the proper Reset procedure:



#### For example:

Let us assume you need to drive the RESET# pad with a totem pole output of a +3/5 V microcontroller (uP\_OUT2):



This signal is internally pulled up so the pin can be left floating if not used.





## 6. Power Supply

The power supply circuitry and board layout are a very important part in the full product design and they strongly reflect on the product overall performances, hence read carefully the requirements and the guidelines that will follow for a proper design.

## 6.1. Power Supply Requirements

POWER SUPPLY (SW release 7.02.xx4 or older)				
Nominal Supply Voltage	3.8 V			
Normal Operating Voltage Range	3.4 V÷ 4.20 V			

POWER SUPPLY (SW release 7.03.x00	or newer)
Nominal Supply Voltage	3.8 V
Normal Operating Voltage Range	3.4 V÷ 4.20 V
Extended Operating Voltage Range	3.22 V÷ 4.50 V



#### NOTE:

The Operating Voltage Range MUST never be exceeded; care must be taken in order to fulfil min/max voltage requirement.



#### NOTE:

Overshoot voltage (regarding MAX Extended Operating Voltage) and drop in voltage (regarding MIN Extended Operating Voltage) MUST never be exceeded;

The "Extended Operating Voltage Range" can be used only with completely assumption and application of the HW User guide suggestions.



#### The Module's power consumptions are:

GE864-QUAD / GC864-QUAD				
Mode	Average (mA)	Mode description		
SWITCHED (	OFF	Module supplied but Switched Off		
Switched Off	<62uA	Module supplied but Switched Off		
		IDLE mode		
AT+CFUN=1	19.0	Normal mode: full functionality of the module		
AT+CFUN=4	18.2	Disabled TX and RX; module is not registered on the network		
	3,9	Paging Multiframe 2		
AT+CFUN=0 or =5	2,8	Paging Multiframe 3		
	2,6	Paging Multiframe 4		
	1,8	Paging Multiframe 9		
CSD TX and RX	mode			
GSM900 CSD PL5	240	GSM VOICE CALL		
DCS1800 CSD PL0	175			
GPRS (class 1) 1	TX + 1RX			
GSM900 PL5	225	GPRS Sending data mode		
DCS1800 PL0	160			
GPRS (class 10) 2	TX + 3RX			
GSM900 PL5 420		GPRS Sending data mode		
DCS1800 PL0	290			

The GSM system is made in a way that the RF transmission is not continuous, else it is packed into bursts at a base frequency of about 216 Hz, the relative current peaks can be as high as about 2A. Therefore the power supply has to be designed in order to withstand with these current peaks without big voltage drops; this means that both the electrical design and the board layout must be designed for this current flow.

If the layout of the PCB is not well designed a strong noise floor is generated on the ground and the supply; this will reflect on all the audio paths producing an audible annoying noise at 216 Hz; if the voltage drop during the peak current absorption is too much, then the device may even shutdown as a consequence of the supply voltage drop.



#### TIP:

The power supply must be designed so that it is capable of a peak current output of at least 2 A.



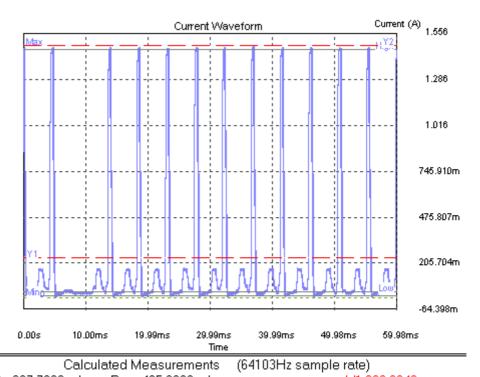


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## 6.1.1. Power consumption Plots

This document section is showing the typical Current consumption plots (using Agilent 66319D) in the normal working conditions of the module.

#### GSM900 - Voice Call - Power level 5

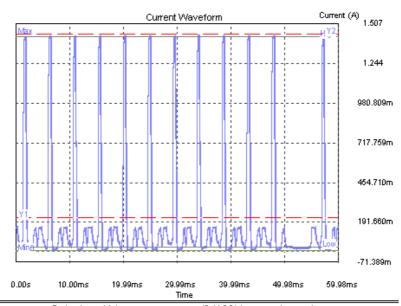






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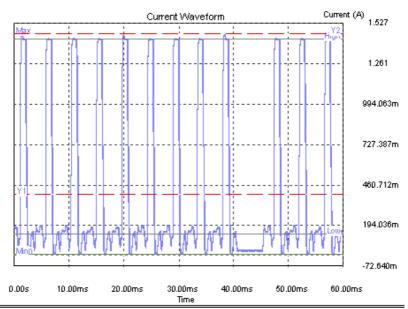
#### GSM900 - GPRS Call - Power level 5 - 1 Slot TX



Calculated Measurements (64103Hz sample rate)

Dc 223.0320mA Rms 465.6530mA Low 28.3425mA Min 3.7677mA High 1.4184A Max 1.4353A Y1 223.2308m Y2 1.4360 dY 1.2128

#### GSM900 - GPRS Call - Power level 5 - 2 Slot TX, 3 Slot RX



Calculated Measurements (64103Hz sample rate)

 Dc 402.5160mA
 Rms 674.0740mA
 Y1 402.2942m

 Low 137.8680mA
 Min 3.5532mA
 Y2 1.4556

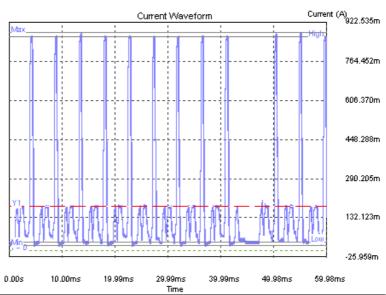
 High 1.4208A
 Mex 1.4549A
 dY 1.0533





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#### DCS1800 - Voice Call - Power level 0



Calculated Measurements

(64103Hz sample rate)

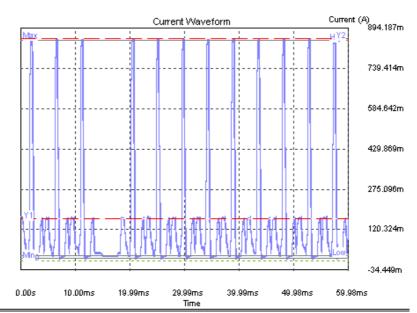
Dc177.1700mA Rms 299.8590mA Low 34.7802mA High 861.7810mA Max 879.5190mA

Min 19.2070mA

Y1 177.6604m Y2 1.4838

dY 1.3061

#### DCS1800 - GPRS Call - Power level 0 - 1 Slot TX



Calculated Measurements

Dc160.0650mA Rms 287.8460mA Low 22.0351mA Min 9.7719mA High 846.7840mA Max 852.0720mA

(64103Hz sample rate)

Y1 160.0650m Y2 852,4848m

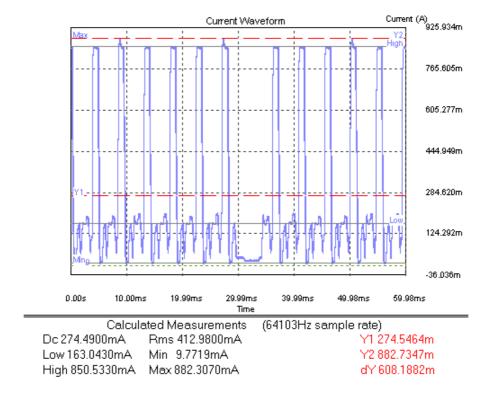
dY 692.4199m





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### PCS1900 - GPRS Call - Power level 0 - 2 Slot TX, 3 Slot RX



## 6.2. General Design Rules

The principal guidelines for the Power Supply Design embrace three different design steps:

- the electrical design
- the thermal design
- the PCB layout.

## 6.2.1. Electrical Design Guidelines

The electrical design of the power supply depends strongly from the power source where this power is drained. We will distinguish them into three categories:

- +5V input (typically PC internal regulator output)
- +12V input (typically automotive)
- Battery

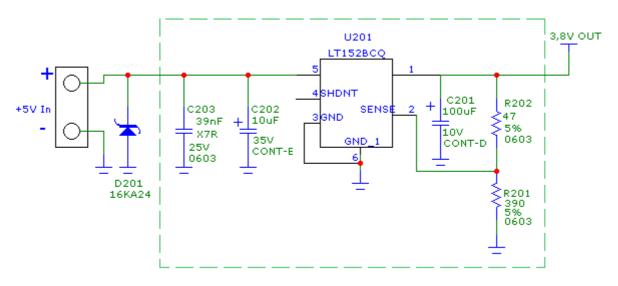




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#### 6.2.1.1. +5V input Source Power Supply Design Guidelines

- The desired output for the power supply is 3.8V, hence there is not a big difference between the input source and the desired output and a linear regulator can be used. A switching power supply will not be suited because of the low drop out requirements.
- When using a linear regulator, a proper heat sink shall be provided in order to dissipate the power generated.
- A Bypass low ESR capacitor of adequate capacity must be provided in order to cut the current absorption peaks close to the GE/GC864-QUAD, a 100µF tantalum capacitor is usually suited.
- Make sure the low ESR capacitor on the power supply output (usually a tantalum one) is rated at least 10V.
- A protection diode must be inserted close to the power input, in order to save the GE/GC864-QUAD from power polarity inversion.



+5VInput Linear Regulator

An example of linear regulator with 5V input is:

#### 6.2.1.2. +12V input Source Power Supply Design Guidelines

 The desired output for the power supply is 3.8V; hence due to the big difference between the input source and the desired output, a linear regulator is not suited and shall not be used. A switching power supply



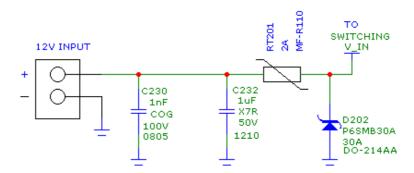


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will be preferable because of its better efficiency especially with the 2A peak current load represented by the GE864-QUAD.

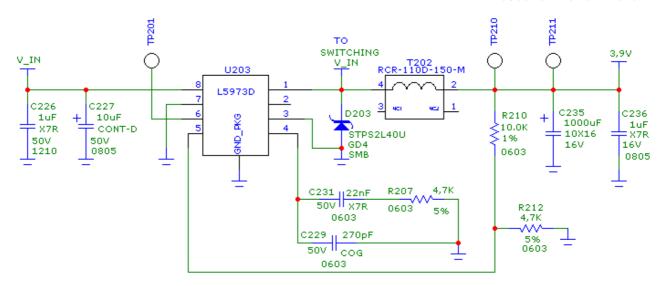
- When using a switching regulator, a 500kHz or more switching frequency regulator is preferable because of its smaller inductor size and its faster transient response. This allows the regulator to respond quickly to the current peaks absorption.
- In any case the frequency and Switching design selection is related to the application to be developed due to the fact the switching frequency could also generate EMC interferences.
- For car PB battery the input voltage can rise up to 15.8V and this must be kept in mind when choosing components: all components in the power supply must withstand this voltage.
- A Bypass low ESR capacitor of adequate capacity must be provided in order to cut the current absorption peaks, a 100µF tantalum capacitor is usually suited.
- Make sure the low ESR capacitor on the power supply output (usually a tantalum one) is rated at least 10V.
- For Car applications a spike protection diode must be inserted close to the power input, in order to clean the supply from spikes.
- A protection diode must be inserted close to the power input, in order to save the GE864-QUAD from power polarity inversion. This can be the same diode as for spike protection.

An example of switching regulator with 12V input is in the below schematic (it is split in 2 parts):





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#### 6.2.1.3. Battery Source Power Supply Design Guidelines

The desired nominal output for the power supply is 3.8V and the maximum voltage allowed is 4.2V (4.5 V if using SW release 7.03.x00 or newer), hence a single 3.7V Lilon cell battery type is suited for supplying the power to the Telit GE864-QUAD module.



#### **CAUTION:**

The three cells Ni/Cd or Ni/MH 3,6 V Nom. battery types or 4V PB types MUST NOT BE USED DIRECTLY since their maximum voltage can rise over the absolute maximum voltage for the GE864-QUAD and damage it.

## **CAUTION:**

DO NOT USE any Ni-Cd, Ni-MH, and Pb battery types directly connected with GE864-QUAD. Their use can lead to overvoltage on the GE864-QUAD and damage it. USE ONLY Li-Ion battery types.

A Bypass low ESR capacitor of adequate capacity must be provided in order to cut the current absorption peaks, a 100µF tantalum capacitor is usually suited.

Make sure the low ESR capacitor (usually a tantalum one) is rated at least 10V.

A protection diode must be inserted close to the power input, in order to save the GE864-QUAD from power polarity inversion. Otherwise the battery connector must be done in a way to avoid polarity inversions when connecting the battery.





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The battery capacity must be at least 500mAh in order to withstand the current peaks of 2A; the suggested capacity is from 500mAh to 1000mAh.

### 6.2.1.4. Battery Charge Control Circuitry Design Guidelines

The charging process for Li-lon Batteries can be divided into 4 phases:

- Qualification and trickle charging
- Fast charge 1 constant current
- Final charge constant voltage or pulsed charging
- Maintenance charge

The qualification process consists in a battery voltage measure, indicating roughly its charge status. If the battery is deeply discharged, that means its voltage is lower than the trickle charging threshold, then the charge must start slowly possibly with a current limited pre-charging process where the current is kept very low with respect to the fast charge value: the trickle charging.

During the trickle charging the voltage across the battery terminals rises; when it reaches the fast charge threshold level the charging process goes into fast charge phase.

During the fast charge phase the process proceeds with a current limited charging; this current limit depends on the required time for the complete charge and from the battery pack capacity. During this phase the voltage across the battery terminals still raises but at a lower rate.

Once the battery voltage reaches its maximum voltage then the process goes into its third state: Final charging. The voltage measure to change the process status into final charge is very important. It must be ensured that the maximum battery voltage is never exceeded, otherwise the battery may be damaged and even explode. Moreover for the constant voltage final chargers, the constant voltage phase (final charge) must not start before the battery voltage has reached its maximum value, otherwise the battery capacity will be highly reduced.

The final charge can be of two different types: constant voltage or pulsed. GE864-QUAD uses constant voltage.

The constant voltage charge proceeds with a fixed voltage regulator (very accurately set to the maximum battery voltage) and hence the current will decrease while the battery is becoming charged. When the charging current falls below a certain fraction of the fast charge current value, then the battery is considered fully charged, the final charge stops and eventually starts the maintenance.

The pulsed charge process has no voltage regulation, instead the charge continues with pulses. Usually the pulse charge works in the following manner: the charge is stopped for some time, let us say few hundreds of ms, then the battery voltage will be measured and when it drops below its maximum value a fixed time length





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charging pulse is issued. As the battery approaches its full charge the off time will become longer, hence the duty-cycle of the pulses will decrease. The battery is considered fully charged when the pulse duty-cycle is less than a threshold value, typically 10%, the pulse charge stops and eventually the maintenance starts.

The last phase is not properly a charging phase, since the battery at this point is fully charged and the process may stop after the final charge. The maintenance charge provides an additional charging process to compensate for the charge leak typical of a Li-lon battery. It is done by issuing pulses with a fixed time length, again few hundreds of ms, and a duty-cycle around 5% or less.

This last phase is not implemented in the GE864-QUAD internal charging algorithm, so that the battery once charged is left discharging down to a certain threshold so that it is cycled from full charge to slight discharge even if the battery charger is always inserted. This guarantees that anyway the remaining charge in the battery is a good percentage and that the battery is not damaged by keeping it always fully charged (Li-Ion rechargeable battery usually deteriorates when kept fully charged).

Last but not least, in some applications it is highly desired that the charging process restarts when the battery is discharged and its voltage drops below a certain threshold, GE864-QUAD internal charger does it.

As you can see, the charging process is not a trivial task to be done; moreover all these operations must start only if battery temperature is inside a charging range, usually  $5^{\circ}\text{C} - 45^{\circ}\text{C}$ .

The GE864-QUAD measures the temperature of its internal component, in order to satisfy this last requirement, it is not exactly the same as the battery temperature but in common application the two temperature must not differ too much and the charging temperature range must be guaranteed.



#### NOTE:

For all the threshold voltages, inside the GE/GC864-QUAD all thresholds are fixed in order to maximize Li-Ion battery performances and do not need to be changed.

#### NOTE:

In this application the battery charger input current must be limited to less than 400mA. This can be done by using a current limited wall adapter as the power source.

#### NOTE:

When starting the charger from Module powered off the startup will be in CFUN4; to activate the normal mode a command AT+CFUN=1 has to be provided. There is also the possibility to activate the normal mode using the ON\_OFF\* signal.





In this case, when HW powering off the module with the same line (ON\_OFF\*) and having the charger still connected, the module will go back to CFUN4.

# NOTE:

It is important having a 100uF Capacitor to VBAT in order to avoid instability of the charger circuit if the battery is accidentally disconnected during the charging activity.

#### NOTE:

When power is supplied to the charge pin, a battery must always be connected to the VBATT pins.



# 6.2.2. Thermal Design Guidelines

The thermal design for the power supply heat sink must be done with the following specifications:

- Average current consumption during transmission @ max PWR level: 500mA
- Average current consumption during transmission @ min PWR level:
   100mA
- Average current during Power Saving (CFUN=5): 4mA
- Average current during idle (Power Saving disabled): 24mA



#### NOTE:

The average consumption during transmissions depends on the power level at which the device is requested to transmit by the network. The average current consumption hence varies significantly.

Considering the very low current during idle, especially if Power Saving function is enabled, it is possible to consider from the thermal point of view that the device absorbs current significantly only during calls.

If we assume that the device stays into transmission for short periods of time (let us say few minutes) and then remains for a quite long time in idle (let us say one hour), then the power supply has always the time to cool down between the calls and the heat sink could be smaller than the calculated one for 500mA maximum RMS current, or even could be the simple chip package (no heat sink).

Moreover in the average network conditions the device is requested to transmit at a lower power level than the maximum and hence the current consumption will be less than the 500mA, being usually around 150mA.

For these reasons the thermal design is rarely a concern and the simple ground plane where the power supply chip is placed can be enough to ensure a good thermal condition and avoid overheating.

For the heat generated by the GE/GC864-QUAD, you can consider it to be during transmission 1W max during CSD/VOICE calls and 2W max during class10 GPRS upload.

This generated heat will be mostly conducted to the ground plane under the GE/GC864-QUAD; you must ensure that your application can dissipate it.





# 6.2.3. Power Supply PCB Layout Guidelines

As seen on the electrical design guidelines the power supply shall have a low ESR capacitor on the output to cut the current peaks and a protection diode on the input to protect the supply from spikes and polarity inversion. The placement of these components is crucial for the correct working of the circuitry. A misplaced component can be useless or can even decrease the power supply performances.

- The Bypass low ESR capacitor must be placed close to the Telit GE/GC864-QUAD power input pads or in the case the power supply is a switching type it can be placed close to the inductor to cut the ripple provided the PCB trace from the capacitor to the GE/GC864-QUAD is wide enough to ensure a dropless connection even during the 2A current peaks.
- The protection diode must be placed close to the input connector where the power source is drained.
- The PCB traces from the input connector to the power regulator IC must be wide enough to ensure no voltage drops occur when the 2A current peaks are absorbed. Note that this is not made in order to save power loss but especially to avoid the voltage drops on the power line at the current peaks frequency of 216 Hz that will reflect on all the components connected to that supply, introducing the noise floor at the burst base frequency. For this reason while a voltage drop of 300-400 mV may be acceptable from the power loss point of view, the same voltage drop may not be acceptable from the noise point of view. If your application does not have audio interface but only uses the data feature of the Telit GE/GC864-QUAD, then this noise is not so disturbing and power supply layout design can be more forgiving.
- The PCB traces to the GE/GC864-QUAD and the Bypass capacitor must be wide enough to ensure no significant voltage drops occur when the 2A current peaks are absorbed. This is for the same reason as previous point. Try to keep this trace as short as possible.
- The PCB traces connecting the Switching output to the inductor and the switching diode must be kept as short as possible by placing the inductor and the diode very close to the power switching IC (only for switching power supply). This is done in order to reduce the radiated field (noise) at the switching frequency (100-500 kHz usually).
- The use of a good common ground plane is suggested.
- The placement of the power supply on the board must be done in such a
  way to guarantee that the high current return paths in the ground plane
  are not overlapped to any noise sensitive circuitry as the microphone
  amplifier/buffer or earphone amplifier.





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• The power supply input cables must be kept separate from noise sensitive lines such as microphone/earphone cables.



# 6.2.4. Parameters for ATEX Application

In order to integrate the Telit's GE/GC864-QUAD modules into an ATEX application, the appropriate reference standard IEC EN xx and integrations shall be followed.

Below are listed parameters and useful information to integrate the module in your application:

• Total capacity: 78.494 μF

• Total inductance: 10.163 μH

- No voltage upper than supply voltage is present in the module.
- No step-up converters are present in the module.
- In abnormal conditions, the maximum RF output power is up to 34 dBm max for few seconds.

For this particular application, we recommend the customer to involve TTSC (Telit Technical Support Center) in the design phase of the application.



# 7. Antenna

The antenna connection and board layout design are the most important part in the full product design and they strongly reflect on the product overall performances, hence read carefully and follow the requirements and the guidelines for a proper design.

# 7.1. GE864-QUAD GSM Antenna Requirements

As suggested on the Product Description the antenna and antenna line on PCB for a Telit GE864-QUAD device shall fulfill the following requirements:

ANTENNA REQUIREMENTS		
Frequency range	Depending by frequency band(s) provided by the network operator, the customer shall use the most suitable antenna for that/those band(s)	
Bandwidth	70 MHz in GSM850, 80 MHz in GSM900, 170 MHz in DCS & 140 MHz PCS band	
Gain	Gain < 3dB <i>i</i>	
Impedance	50 Ω	
Input power	> 2 W peak power	
VSWR absolute max	<= 10:1	
VSWR recommended	<= 2:1	

When using the Telit GE864-QUAD, since there is no antenna connector on the module, the antenna must be connected to the GE864-QUAD through the PCB with the antenna pad.

In the case that the antenna is not directly developed on the same PCB, hence directly connected at the antenna pad of the GE864-QUAD, then a PCB line is needed in order to connect with it or with its connector.

This line of transmission shall fulfill the following requirements:

ANTENNA LINE ON PCB REQUIREMENTS		
Impedance 50 Ω		
Max Attenuation 0,3 dB		
No coupling with other signals allowed		
Cold End (Ground Plane) of antenna shall be		
equipotential to the GE864-QUAD ground pins		





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Furthermore if the device is developed for the US market and/or Canada market, it shall comply to the FCC and/or IC approval requirements:

This device is to be used only for mobile and fixed application. The antenna(s) used for this transmitter must be installed to provide a separation distance of at least 20 cm from all persons and must not be co-located or operating in conjunction with any other antenna or transmitter. End-Users must be provided with transmitter operation conditions for satisfying RF exposure compliance. OEM integrators must ensure that the end user has no manual instructions to remove or install the GE864-QUAD module. Antennas used for this OEM module must not exceed 3dBi gain for mobile and fixed operating configurations.

## 7.2. GE864-QUAD GSM Antenna – PCB Line Guidelines

- Ensure that the antenna line impedance is  $50\Omega$ ;
- Keep the antenna line on the PCB as short as possible, since the antenna line loss shall be less than 0,3 dB;
- Antenna line must have uniform characteristics, constant cross section, avoid meanders and abrupt curves;
- Keep, if possible, one layer of the PCB used only for the Ground plane;
- Surround (on the sides, over and under) the antenna line on PCB with Ground, avoid having other signal tracks facing directly the antenna line track;
- The ground around the antenna line on PCB has to be strictly connected to the Ground Plane by placing vias once per 2mm at least;
- Place EM noisy devices as far as possible from GE864-QUAD antenna line;
- Keep the antenna line far away from the GE864-QUAD power supply lines;
- If you have EM noisy devices around the PCB hosting the GE864-QUAD, such as fast switching ICs, take care of the shielding of the antenna line by burying it inside the layers of PCB and surround it with Ground planes, or shield it with a metal frame cover.
- If you do not have EM noisy devices around the PCB of GE864-QUAD, by using a strip-line on the superficial copper layer for the antenna line, the line attenuation will be lower than a buried one;



# 7.3. GC864-QUAD GSM Antenna Requirements

As suggested on the Product Description the antenna for a Telit GC864-QUAD device shall fulfill the following requirements:

ANTENNA REQUIREMENTS		
Frequency range	Depending by frequency band(s) provided by the network operator, the customer shall use the most suitable antenna for that/those band(s)	
Bandwidth	70 MHz in GSM850, 80 MHz in GSM900, 170 MHz in DCS & 140 MHz PCS band	
Gain	Gain < 1,4dBi in GSM 850 & 900 and < 3,0dBi DCS & PCS	
Impedance	50 Ω	
Input power	> 2 W peak power	
VSWR absolute max	<= 10:1	
VSWR recommended	<= 2:1	

Furthermore if the device is developed for the US market and/or Canada market, it shall comply to the FCC and/or IC approval requirements:

This device is to be used only for mobile and fixed application. The antenna(s) used for this transmitter must be installed to provide a separation distance of at least 20 cm from all persons and must not be co-located or operating in conjunction with any other antenna or transmitter. End-Users must be provided with transmitter operation conditions for satisfying RF exposure compliance. OEM integrators must ensure that the end user has no manual instructions to remove or install the GC864-QUAD / PY module. Antennas used for this OEM module must not exceed 3dBi gain for mobile and fixed operating configurations.

# 7.4. GSM Antenna – Installation Guidelines

- Install the antenna in a place covered by the GSM signal.
- The Antenna must be installed to provide a separation distance of at least 20 cm from all persons and must not be co-located or operating in conjunction with any other antenna or transmitter;
- Antenna shall not be installed inside metal cases
- Antenna shall be installed also according Antenna manufacturer instructions.





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# 8. Logic Level Specifications

Where not specifically stated, all the interface circuits work at 2.8V CMOS logic levels. The following table shows the logic level specifications used in the Telit GE/GC864-QUAD interface circuits:

# Absolute Maximum Ratings -Not Functional

Parameter	Min	Max
Input level on any	-0.3V	+3.6V
digital pin when on		
Input voltage on analog	-0.3V	+3.0 V
pins when on		

# Operating Range - Interface Levels (2.8V CMOS)

Level	Min	Max
Input high level	2.1V	3.3V
Input low level	0V	0.5V
Output high level	2.2V	3.0V
Output low level	0V	0.35V

#### For 1.8V signals:

## Operating Range - Interface Levels (1.8V CMOS)

Level	Min	Max
Input high level	1.6V	2.2V
Input low level	0V	0.4V
Output high level	1,65V	2.2V
Output low level	0V	0.35V

### **Current Characteristics**

Level	Typical
Output Current	1mA
Input Current	1uA



# 8.1. Reset Signal

Signal	Function	1/0	Bga Ball
RESET	Phone reset		A2

RESET is used to reset the GE/GC864-QUAD modules. Whenever this signal is pulled low, the GE/GC864-QUAD is reset. When the device is reset it stops any operation. After the release of the reset GE/GC864-QUAD is unconditionally shut down, without doing any detach operation from the network where it is registered. This behavior is not a proper shut down because any GSM device is requested to issue a detach request on turn off. For this reason the Reset signal must not be used to normally shutting down the device, but only as an emergency exit in the rare case the device remains stuck waiting for some network response.

The RESET is internally controlled on start-up to achieve always a proper power-on reset sequence, so there is no need to control this pin on start-up. It may only be used to reset a device already on that is not responding to any command.



#### NOTE:

Do not use this signal to power off the GE/GC864-QUAD. Use the ON/OFF signal to perform this function or the AT#SHDN command.

## Reset Signal Operating Levels:

Signal	Min	Max
RESET Input high	2.0V*	2.2V
RESET Input low	0V	0.2V

This signal is internally pulled up so the pin can be left floating if not used.

If unused, this signal may be left unconnected. If used, then it **must always be connected with an open collector transistor**, to permit to the internal circuitry the power on reset and under voltage lockout functions.



# 9. Serial Ports

The serial port on the Telit GE864-QUAD is the core of the interface between the module and OEM hardware.

2 serial ports are available on the module:

- MODEM SERIAL PORT
- MODEM SERIAL PORT 2 (DEBUG)

## 9.1. Modem Serial Port

Several configurations can be designed for the serial port on the OEM hardware, but the most common are:

- RS232 PC com port
- Micro controller UART @ 2.8V 3V (Universal Asynchronous Receive Transmit)
- Micro controller UART@ 5V or other voltages different from 2.8V

Depending from the type of serial port on the OEM hardware a level translator circuit may be needed to make the system work. The only configuration that does not need a level translation is the 2.8V UART.

The serial port on the GE864-QUAD is a +2.8V UART with all the 7 RS232 signals. It differs from the PC-RS232 in the signal polarity (RS232 is reversed) and levels. The levels for the GE864-QUAD UART are the CMOS levels:

## Absolute Maximum Ratings - Not Functional

Parameter	Min	Max
Input level on any	-0.3V	+3.6V
digital pad when on		
Input voltage on	-0.3V	+3.0 V
analog pads when on		



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# Operating Range - Interface Levels (2.8V CMOS)

Level	Min	Max
Input high level V <sub>IH</sub>	2.1V	3.3V
Input low level $V_{_{IL}}$	0V	0.5V
Output high level V <sub>OH</sub>	2.2V	3.0V
Output low level V <sub>OL</sub>	0V	0.35V



## The table below shows the signals of the GE864 serial port:

RS232 Pin Number	Signal	GE864-QUAD Pad Number	Name	Usage
1	DCD – dcd_uart	D9	Data Carrier Detect	Output from the GE864-QUAD that indicates the carrier presence
2	RXD – tx_uart	H8	Transmit line * see Note	Output transmit line of GE864-QUAD UART
3	TXD – rx_uart	E7	Receive line *see Note	Input receive of the GE864-QUAD UART
4	DTR – dtr_uart	B7	Data Terminal Ready	Input to the GE864-QUAD that controls the DTE READY condition
5	GND	A1,F1,H1,L1, H2, L2, J3, K3	Ground	ground
6	DSR – dsr_uart	E11	Data Set Ready	Output from the GE864-QUAD that indicates the module is ready
7	RTS – rts_uart	F7	Request to Send	Input to the GE864-QUAD that controls the Hardware flow control
8	CTS – cts_uart	F6	Clear to Send	Output from the GE864-QUAD that controls the Hardware flow control
9	RI – ri_uart	B6	Ring Indicator	Output from the GE864-QUAD that indicates the incoming call condition

# The table below shows the signals of the GC864-QUAD serial port:

RS232 Pin Number	Signal	GC864- QUAD Pad Number	Name	Usage
1	DCD – dcd_uart	32	Data Carrier Detect	Output from the GC864-QUAD that indicates the carrier presence
2	RXD – tx_uart	26	Transmit line *see Note	Output transmit line of GC864-QUAD UART
3	TXD – rx_uart	25	Receive line *see Note	Input receive of the GC864-QUAD UART
4	DTR – dtr_uart	29	Data Terminal Ready	Input to the GC864-QUAD that controls the DTE READY condition
5	GND	5,6,7	Ground	ground
6	DSR – dsr_uart	27	Data Set Ready	Output from the GC864-QUAD that indicates the module is ready
7	RTS – rts_uart	31	Request to Send	Input to the GC864-QUAD that controls the Hardware flow control
8	CTS – cts_uart	28	Clear to Send	Output from the GC864-QUAD that controls the Hardware flow control
9	RI – ri_uart	30	Ring Indicator	Output from the GC864-QUAD that indicates the incoming call condition























#### \*NOTE:

According to V.24, RX/TX signal names are referred to the application side, therefore on the GE864 side these signal are on the opposite direction: TXD on the application side will be connected to the receive line (here named TXD/ rx\_uart ) of the GE864 serial port and vice versa for RX.



#### TIP:

For a minimum implementation, only the TXD and RXD lines can be connected, the other lines can be left open provided a software flow control is implemented.

#### TIP:

In order to avoid noise or interferences on the RXD lines it is suggested to add a pull up resistor (100K  $\Omega$  to 2.8V)



# 9.2. RS232 Level Translation

In order to interface the Telit GE864 with a PC com port or a RS232 (EIA/TIA-232) application a level translator is required. This level translator must

- invert the electrical signal in both directions
- change the level from 0/3V to +15/-15V

Actually, the RS232 UART 16450, 16550, 16650 & 16750 chipsets accept signals with lower levels on the RS232 side (EIA/TIA-562), allowing for a lower voltage-multiplying ratio on the level translator. Note that the negative signal voltage must be less than 0V and hence some sort of level translation is always required.

The simplest way to translate the levels and invert the signal is by using a single chip level translator. There are a multitude of them, differing in the number of driver and receiver and in the levels (be sure to get a true RS232 level translator not a RS485 or other standards).

By convention the driver is the level translator from the 0-3V UART level to the RS232 level, while the receiver is the translator from RS232 level to 0-3V UART.

In order to translate the whole set of control lines of the UART you will need:

- 5 driver
- 3 receiver



#### NOTE:

The digital input lines working at 2.8VCMOS have an absolute maximum input voltage of 3,75V; therefore the level translator IC shall not be powered by the +3.8V supply of the module. Instead it shall be powered from a +2.8V / +3.0V (dedicated) power supply.

This is because in this way the level translator IC outputs on the module side (i.e. GE864 inputs) will work at +3.8V interface levels, stressing the module inputs at its maximum input voltage.

This can be acceptable for evaluation purposes, but not on production devices.

#### NOTE:

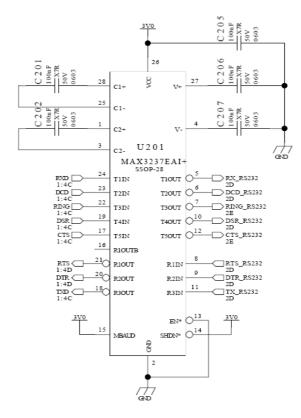
In order to be able to do in circuit reprogramming of the GE864 firmware, the serial port on the Telit GE864 shall be available for translation into RS232 and either it is controlling device shall be placed into tristate, disconnected or as a gateway for the serial data when module reprogramming occurs.

Only RXD, TXD, GND and the On/off module turn on pad are required to the reprogramming of the module, the other lines are unused.

All applicator shall include in their design such a way of reprogramming the GE864.



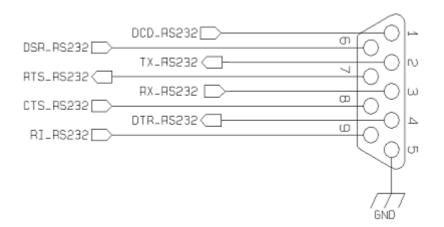




RS232 LEVEL TRSANSLATOR

An example of level translation circuitry of this kind is:

The RS232 serial port lines are usually connected to a DB9 connector with the following layout:



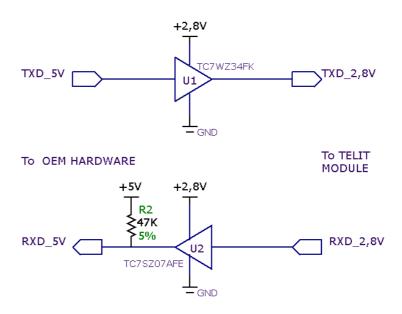




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# 9.3. 5V UART Level Translation

If the OEM application uses a microcontroller with a serial port (UART) that works at a voltage different from 2.8-3V, then a circuitry has to be provided to adapt the different levels of the two sets of signals. As for the RS232 translation there are a multitude of single chip translators. For example a possible translator circuit for a 5V TRANSMITTER/RECEIVER can be:





#### TIP:

This logic IC for the level translator and 2.8V pull-ups (not the 5V one) can be powered directly from VAUX line of the GE/GC864-QUAD. Note that the TC7SZ07AE has open drain output; therefore the resistor R2 is mandatory.



#### TIP:

The UART input line TXD (rx\_uart) of the GE/GC864-QUAD is NOT internally pulled up with a resistor, so there may be the need to place an external 47K $\Omega$  pull-up resistor, either the DTR (dtr\_uart) and RTS (rts\_uart) input lines are not pulled up internally, so an external pull-up resistor of 47K $\Omega$  may be required.





A power source of the internal interface voltage corresponding to the 2.8VCMOS high level is available at the VAUX pin on the connector,

A maximum of 9 resistors of 47 K $\Omega$  pull-up can be connected to the PWRMON pin, provided no other devices are connected to it and the pulled-up lines are GE/GC864-QUAD input lines connected to open collector outputs in order to avoid latch-up problems on the GE/GC864-QUAD.

Care must be taken to avoid latch-up on the GE/GC864-QUAD and the use of this output line to power electronic devices shall be avoided, especially for devices that generate spikes and noise such as switching level translators, micro controllers, failure in any of these condition can severely compromise the GE/GC864-QUAD functionality.



#### NOTE:

The input lines working at 2.8VCMOS can be pulled-up with  $47 \text{K}\Omega$  resistors that can be connected directly to the VAUX line provided they are connected as in this example.

In case of reprogramming of the module has to be considered the use of the RESET line to start correctly the activity.

The preferable configuration is having an external supply for the buffer.



# 10. Audio Section Overview

The Baseband chip was developed for the cellular phones, which needed two separated amplifiers both in RX and in TX section.

A couple of amplifiers had to be used with internal audio transducers while the other couple of amplifiers had to be used with external audio transducers.

To distinguish the schematic signals and the Software identifiers, two different definitions were introduced, with the following meaning:

- internal audio transducers → HS/MT (from HandSet or MicroTelephone)
- external audio transducers → HF (from HandsFree)

Actually the acronyms have not the original importance.

In other words this distinction is not necessary, being the performances between the two blocks like the same.

Only if the customer needs higher output power to the speaker, he has a constraint. Otherwise the choice could be done in order to overcome the PCB design difficulties.

For these reasons we have not changed the HS and HF acronyms, keeping them in the Software and on the schematics.

The Base Band Chip of the GE864Telit Module maintains the same architecture.

For more information refer to Telit document:

" 80000NT10007a Audio Settings Application Note".

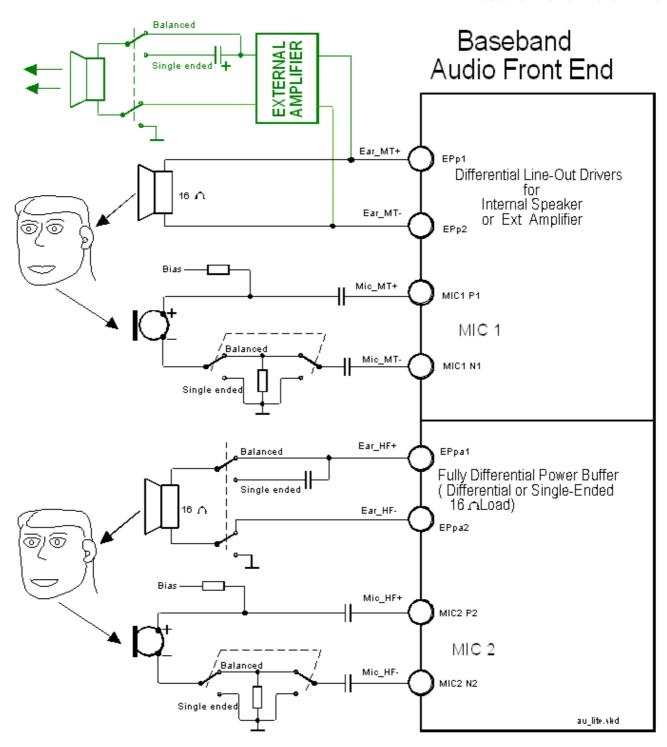
## 10.1. Selection mode

Only one block can be active at a time, and the activation of the requested audio path is done via hardware by **AXE** line or via software by **AT#CAP** command.

Moreover the Sidetone functionality could be implemented by the amplifier fitted between the transmit path and the receive path, enabled at request in both modes.



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Audio Section Block Diagram





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## 10.2. Electrical Characteristics



TIP: Being the microphone circuitry the more noise sensitive, its design and layout must be done with particular care. Both microphone paths are balanced and the OEM circuitry must be balanced designed to reduce the common mode noise typically generated on the ground plane. However the customer can use the unbalanced circuitry for particular application.

# 10.2.1. Input Lines Characteristics

"MIC_MT" and "MIC_HF" di	fferential microphone paths		
Line Coupling	AC*		
Line Type	Balanced		
Coupling capacitor	≥ 100nF		
Differential input resistance	<b>50k</b> Ω		
Differential input voltage	$\leq$ 1,03V <sub>pp</sub> @ $MicG=0dB$		



(\*) WARNING: AC means that the signals from the microphone have to be connected to input lines of the module through capacitors which value has to be  $\geq 100$ nf. not respecting this constraint, the input stages will be damaged.

**WARNING:** when particular OEM application needs a *Single Ended Input* configuration, it is forbidden connecting the unused input directly to Ground, but only through a 100nF capacitor. Don't forget that in Single Ended configuration the useful input signal will be halved.



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# 10.2.2. Output Lines Characteristics

"EAR_MT" Output Lines					
line coupling	AC single-ended				
	DC differential				
output load resistance	≥ 14 Ω				
internal output resistance	4 Ω ( <i>typical</i> )				
signal bandwidth	150 - 4000 Hz @ -3 dB				
max. differential output voltage	1.31 V <sub>rms</sub> ( <i>typical, open circuit</i> )				
differential output voltage	328mV <sub>rms</sub> /16 Ω / <i>@ -12dBFS</i>				
volume increment	2 dB per step				
volume steps	10				

"EAR_HF" Output Lines			
line coupling:	AC single-ended		
	DC differential		
output load resistance :	≥ 14 Ω		
internal output resistance:	4 Ω (>1,7 Ω)		
signal bandwidth:	150 - 4000 Hz @ -3 dB		
max. differential output	1.31 V <sub>rms</sub> ( <i>typical, open circuit</i> )		
voltage			
max. S.E. output voltage	656 mV <sub>rms</sub> ( <i>typical, open circuit</i> )		
volume increment	2 dB per step		
volume steps	10		



## TIP:

We suggest driving the load differentially from both output drivers, thus the output swing will double and the need for the output coupling capacitor avoided. However if particular OEM application needs also a Single Ended circuitry can be implemented, but the output power will be reduced four times.

The OEM circuitry shall be designed to reduce the common mode noise typically generated on the ground plane and to get the maximum power output from the device (low resistance tracks).







#### **WARNING:**

The loads are directly connected to the amplifier outputs when in *Differential* configuration, through a capacitor when in *Single Ended* configuration. Using Single Ended configuration, the unused output line must be left open. Not respecting this constraint, the output stage will be damaged.



#### TIP:

Remember that there are slightly different electrical performances between the two internal audio amplifiers:

- the "Ear\_MT" lines can directly drive a 16  $\Omega$  load at -12dBFS (\*\*) in Differential configuration
- the "Ear\_HF" lines can directly drive a 16Ω load in Differential or Single Ended configurations
- There is no difference if the amplifiers drive an external amplifier

(\*\*) OdBFS is the normalized overall Analog Gain for each Output channel equal to  $3,7V_{op}$  differential



# 11. External SIM Holder Implementation

Please refer to the related Telit User Guide:

"80000NT10001a SIM Holder Design Guides"



# 12. General Purpose I/O

The general purpose I/O pads can be configured to act in three different ways:

- input
- output
- alternate function (internally controlled)

Input pads can only be read and report the digital value (high or low) present on the pad at the read time; output pads can only be written or queried and set the value of the pad output; an alternate function pad is internally controlled by the GE/GC864-QUAD firmware and acts depending on the function implemented. For Logic levels please refer to chapter 7.

The following GPIO are available on the GE864-QUAD:

Ball	Signal	1/0	Function	Туре	Input / output current	Default State	ON_OFF state	State during Reset	Note
C1	TGPIO_01	1/0	GPI001 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
E6	TGPI0_02	1/0	GPI002 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		Alternate function (JDR)
C2	TGPI0_03	1/0	GPI003 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
В3	TGPI0_04	1/0	GPI004 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		Alternate function (RF Transmission Control)
К8	TGPI0_05	1/0	GPI005 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		Alternate function (RFTXMON)
B5	TGPI0_06	1/0	GPI006 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	Pict 01	1	Alternate function (ALARM)
L9	TGPI0_07	1/0	GPI007 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		Alternate function (BUZZER)
K11	TGPIO_08	1/0	GPI008 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
C9	TGPIO_09	1/0	GPI009 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
Н3	TGPIO_10	1/0	GPI010 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
D1	TGPIO_11	1/0	GPI011 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
G4	TGPIO_12	1/0	GPI012 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
K10	TGPIO_13	1/0	GPI013 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
B4	TGPIO_14	1/0	GPI014 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
F5	TGPIO_15	1/0	GPI015 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
Н6	TGPIO_16	1/0	GPI016 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
H5	TGPIO_17	1/0	GPI017 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
K7	TGPIO_18	1/0	GPI018 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
B1	TGPIO_19	1/0	GPI019 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
С3	TGPI0_20	1/0	GPI020 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
L10	TGPIO_21	1/0	GPI021 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	1		
E8	TGPI0_22	1/0	GPI022 Configurable GPI0	CMOS 1.8V (not 2.8V !!)	1uA / 1mA	INPUT	0		



### The following GPIO are available on the GC864-QUAD:

Pin	Signal	1/0	Function	Туре	Input / output current	Default State	ON_OFF state	State during Reset	Note
70	TGPI0_01	1/0	GPI001 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
74	TGPI0_02	1/0	GPI002 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		Alternate function (JDR)
66	TGPI0_03	1/0	GPI003 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
59	TGPI0_04	1/0	GPI004 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		Alternate function (RF Transmission Control)
78	TGPI0_05	1/0	GPI005 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		Alternate function (RFTXMON)
68	TGPI0_06	1/0	GPI006 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	Pict 01	1	Alternate function (ALARM)
73	TGPIO_07	1/0	GPI007 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		Alternate function (BUZZER)
67	TGPI0_08	1/0	GPI008 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
76	TGPI0_09	1/0	GPI009 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
63	TGPIO_10	1/0	GPI010 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
57	TGPI0_11	1/0	GPI011 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
62	TGPIO_12	1/0	GPI012 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
77	TGPI0_13	1/0	GPI013 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
60	TGPI0_14	1/0	GPI014 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
61	TGPIO_15	1/0	GPI015 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
75	TGPIO_16	1/0	GPI016 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
71	TGPIO_17	1/0	GPI017 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
65	TGPIO_18	1/0	GPI018 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
56	TGPI0_19	1/0	GPI019 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
58	TGPI0_20	1/0	GPI020 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	0		
72	TGPI0_21	1/0	GPI021 Configurable GPI0	CMOS 2.8V	1uA / 1mA	INPUT	1		
64	TGPI0_22	1/0	GPI022 Configurable GPI0	CMOS 1.8V (not 2.8V !!)	1uA / 1mA	INPUT	0		

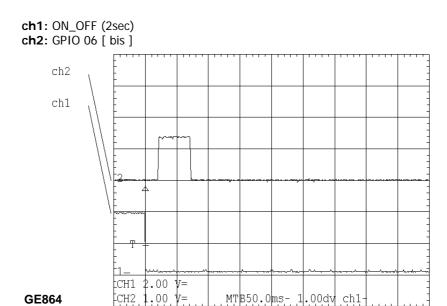
## Not all GPIO pads support all these three modes:

- GPIO2 supports all three modes and can be input, output, Jamming Detect Output (Alternate function)
- GPI04 supports all three modes and can be input, output, RF Transmission Control (Alternate function)
- GPI05 supports all three modes and can be input, output, RFTX monitor output (Alternate function)
- GPI06 supports all three modes and can be input, output, alarm output (Alternate function)



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• GPI07 supports all three modes and can be input, output, buzzer output (Alternate function)





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# 12.1. GPIO Logic Levels

Where not specifically stated, all the interface circuits work at 2.8V CMOS logic levels.

The following tables show the logic level specifications used in the GE864-QUAD interface circuits:

# Absolute Maximum Ratings - Not Functional

Parameter	Min	Max
Input level on any	-0.3V	+3.6V
digital pin when on		
Input voltage on	-0.3V	+3.0 V
analog pins when on		

# Operating Range - Interface Levels (2.8V CMOS)

Level	Min	Max
Input high level	2.1V	3.3V
Input low level	0V	0.5V
Output high level	2.2V	3.0V
Output low level	0V	0.35V

### For 1.8 V signals:

### Operating Range – Interface Levels (1.8V CMOS)

Level	Min	Max
Input high level	1.6V	2.2V
Input low level	0V	0.4V
Output high level	1,65V	2.2V
Output low level	0V	0.35V



# 12.2. Using a GPIO Pad as INPUT

The GPIO pads, when used as inputs, can be connected to a digital output of another device and report its status, provided this device has interface levels compatible with the 2.8V CMOS levels of the GPIO.

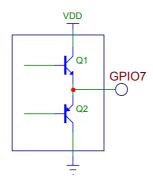
If the digital output of the device to be connected with the GPIO input pad has interface levels different from the 2.8V CMOS, then it can be buffered with an open collector transistor with a 47K pull up to 2.8V.

# 12.3. Using a GPIO Pad as OUTPUT

The GPIO pads, when used as outputs, can drive 2.8V CMOS digital devices or compatible hardware. When set as outputs, the pads have a push-pull output and therefore the pull-up resistor may be omitted.

The illustration below shows the base circuit of a push-pull stage:

# 12.4. Using the RF Transmission Control GPI04



The GPIO4 pin, when configured as RF Transmission Control Input, permits to disable the Transmitter when the GPIO is set to Low by the application.

In the design is necessary to add a pull up resistor (47K to VAUX).

# 12.5. Using the RFTXMON Output GPI05

The GPIO5 pin, when configured as RFTXMON Output, is controlled by the GE/GC864-QUAD module and will rise when the transmitter is active and fall after the transmitter activity is completed.

For example, if a call is started, the line will be HIGH during all the conversation and it will be again LOW after hanged up.

The line rises up 300ms before first TX burst and will became again LOW from 500ms to 1sec after last TX burst.





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# 12.6. Using the Alarm Output GPIO6

The GPIO6 pad, when configured as Alarm Output, is controlled by the GE/GC864-QUAD module and will rise when the alarm starts and fall after the issue of a dedicated AT command.

This output can be used to power up the GE/GC864-QUAD controlling micro controller or application at the alarm time, giving you the possibility to program a timely system wake-up to achieve some periodic actions and completely turn off either the application and the GE/GC864-QUAD during sleep periods, dramatically reducing the sleep consumption to few  $\mu A$ .

In battery-powered devices this feature will greatly improve the autonomy of the device.



#### NOTE:

During RESET the line is set to HIGH logic level.



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# 12.7. Using the Buzzer Output GPI07

As *Alternate Function*, the GPIO7 is controlled by the firmware that depends on the function implemented internally.

This setup places always the GPI07 pin in *OUTPUT* direction and the corresponding function must be activated properly by **AT#SRP** command (refer to *AT commands specification*).

Also in this case, the *dummy value* for the pin state can be both " $\mathcal{O}$ " or " $\mathcal{I}$ ".

Send the command AT#GPI0=7, 1, 2<cr>:

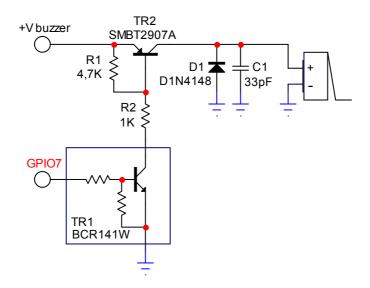
Wait for response

OK

• Send the command AT#SRP=3

The GPI07 pin will be set as *Alternate Function* pin with its dummy logic status set to *HIGH* value.

The "Alternate function" permits your application to easily implement **Buzzer** feature with some small hardware extension of your application as shown in the sample figure below.



Example of Buzzer's driving circuit



#### NOTE:

To correctly drive a buzzer, a driver must be provided; its characteristics depend on the Buzzer and for them refer to your buzzer vendor.



## 12.8. Using the Temperature Monitor Function

## 12.8.1. Short Description

The Temperature Monitor is a function of the module that permits to control its internal temperature and if properly set (see the #TEMPMON command on AT Interface guide) it raise to High Logic level a GPIO when the maximum temperature is reached.

#### 12.8.2. Allowed GPIO

The AT#TEMPMON set command could be used with one of the following GPIO:

Ball (for GE only)	Signal	Function	Туре	Input / output current	Note
C1	TGPIO_01	GPI001 Configurable GPI0	CMOS 2.8V	1μ <b>A / 1mA</b>	
C2	TGPI0_03	GPI003 Configurable GPI0	CMOS 2.8V	1μ <b>A / 1mA</b>	
K11	TGPI0_08	GPI008 Configurable GPI0	CMOS 2.8V	1μA / 1mA	
C9	TGPI0_09	GPI009 Configurable GPI0	CMOS 2.8V	1μA / 1mA	
Н3	TGPIO_10	GPI010 Configurable GPI0	CMOS 2.8V	1μA / 1mA	
D1	TGPIO_11	GPI011 Configurable GPI0	CMOS 2.8V	1μA / 1mA	
G4	TGPIO_12	GPI012 Configurable GPI0	CMOS 2.8V	1μA / 1mA	
K10	TGPIO_13	GPI013 Configurable GPI0	CMOS 2.8V	1μA / 1mA	
B4	TGPIO_14	GPI014 Configurable GPI0	CMOS 2.8V	1μ <b>A / 1mA</b>	
F5	TGPIO_15	GPI015 Configurable GPI0	CMOS 2.8V	1μ <b>A / 1mA</b>	
H6	TGPIO_16	GPI016 Configurable GPI0	CMOS 2.8V	1μA / 1mA	
H5	TGPIO_17	GPI017 Configurable GPI0	CMOS 2.8V	1μ <b>A / 1mA</b>	
K7	TGPIO_18	GPI018 Configurable GPI0	CMOS 2.8V	1μ <b>A / 1mA</b>	
B1	TGPIO_19	GPI019 Configurable GPI0	CMOS 2.8V	1μ <b>A / 1mA</b>	
C3	TGPI0_20	GPI020 Configurable GPI0	CMOS 2.8V	1μ <b>A / 1mA</b>	
E8	TGPIO_22	GPI022 Configurable GPI0	CMOS 1.8V (not 2.8V !!)	1μA / 1mA	

The set command could be used also with one of the following GPIO but in that case the alternate function is not usable:

Ball	Signal	Function	Туре	Input / output current	Note
E6	TGPI0_02	GPI002 Configurable GPI0	CMOS 2.8V	1μA / 1mA	Alternate function (JDR)
В3	TGPI0_04	GPI004 Configurable GPI0	CMOS 2.8V	1μ <b>A / 1mA</b>	Alternate function (RF Transmission Control)
K8	TGPI0_05	GPI005 Configurable GPI0	CMOS 2.8V	1μA / 1mA	Alternate function (RFTXMON)
L9	TGPI0_07	GPI007 Configurable GPI0	CMOS 2.8V	1μA / 1mA	Alternate function (BUZZER)



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## 12.9. Indication of Network Service Availability

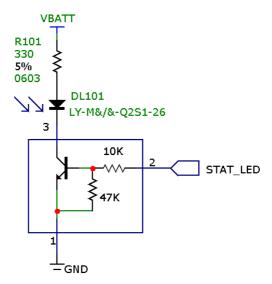
The STAT\_LED pin status shows information on the network service availability and Call status.

In the GE864 modules, the STAT\_LED usually needs an external transistor to drive an external LED.

Therefore, the status indicated in the following table is reversed with respect to the pin status.

LED status	Device Status	
Permanently off	Device off	
_	Net search / Not registered / turning off	
Slow blinking (Period 3s, Ton 0,3s)	Registered full service	
Permanently on	a call is active	

A schematic example could be:





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## 12.10. RTC Bypass Out

The VRTC pin brings out the Real Time Clock supply, which is separate from the rest of the digital part, allowing having only RTC going on when all the other parts of the device are off.

To this power output a backup capacitor can be added in order to increase the RTC autonomy during power off of the battery. NO Devices must be powered from this pin.

## 12.11. VAUX1 Power Output

A regulated power supply output is provided in order to supply small devices from the module.

This output is active when the module is ON and goes OFF when the module is shut down.

The operating range characteristics of the supply are:

Operating Range - VAUX1 power supply

	Min	Typical	Max
Output voltage	2.75V	2.85V	2.95V
Output current			100mA
Output bypass capacitor (inside the module)			2.2μF



## 13. DAC and ADC Section

#### 13.1. DAC Converter

## 13.1.1. Description

The GE/GC864-QUAD module provides a Digital to Analog Converter. The signal (named DAC\_OUT) is available on BGA Ball C7 of the GE/GC864-QUAD module and on pin 17 of PL102 on EVK2 Board (CS1152).

The on board DAC is a 10-bit converter, able to generate a analogue value based a specific input in the range from 0 up to 1023. However, an external low-pass filter is necessary

	Min	Max	Units
Voltage range (filtered)	0	2,6	Volt
Range	0	1023	Steps

The precision is 10 bits so, if we consider that the maximum voltage is 2V, the integrated voltage could be calculated with the following formula:

#### Integrated output voltage = 2 \* value / 1023

DAC\_OUT line must be integrated (for example with a low band pass filter) in order to obtain an analog voltage.

## 13.1.2. Enabling DAC

The AT command below is available to use the DAC function:

AT#DAC[=<enable>[,<value>]]

<value> - scale factor of the integrated output voltage (0..1023 - 10 bit precision)
it must be present if <enable>=1

Refer to SW User Guide or AT Commands Reference Guide for the full description of this function.



#### NOTE:

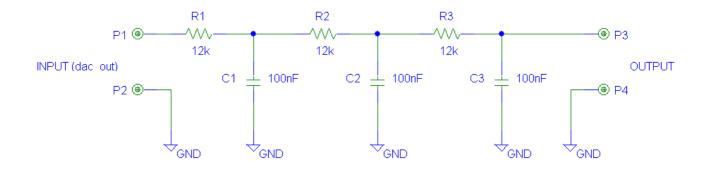
The DAC frequency is selected internally. D/A converter must not be used during POWERSAVING.





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## 13.1.3. Low Pass Filter Example



#### 13.2. ADC Converter

## 13.2.1. Description

The on board A/D are 11-bit converter. They are able to read a voltage level in the range of  $0 \div 2$  volts applied on the ADC pin input, store and convert it into 11 bit word.

	Min	Max	Units
Input Voltage range	0	2	Volt
AD conversion	-	11	bits
Resolution	-	< 1	mV

The GE/GC864-QUAD module provides 3 Analog to Digital Converters. The input lines are:

ADC\_IN1 available on Ball J11 and Pin 19 of PL102 on EVK2 Board (CS1152).

ADC\_IN2 available on Ball H11 and Pin 20 of PL102 on EVK2 Board (CS1152).

ADC\_IN3 available on Ball G11 and Pin 21 of PL102 on EVK2 Board (CS1152).

## 13.2.2. Using ADC Converter

The AT command below is available to use the ADC function:

#### AT#ADC=1.2

The read value is expressed in mV

Refer to SW User Guide or AT Commands Reference Guide for the full description of this function.





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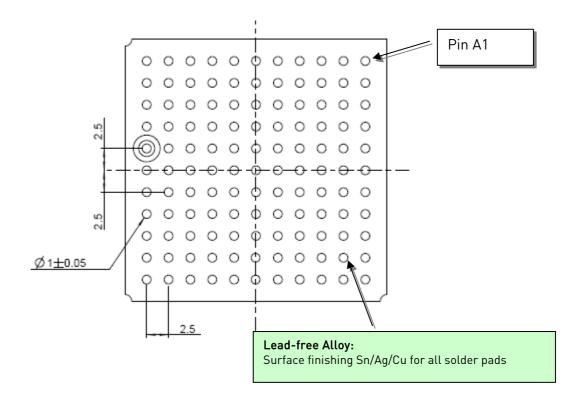
# 14. Mounting the GE/GC864-QUAD on the application board

## 14.1. GE864-QUAD

## 14.1.1. General

The Telit GE864 modules have been designed in order to be compliant with a standard lead-free SMT process.

## 14.1.2. Module Finishing & Dimensions

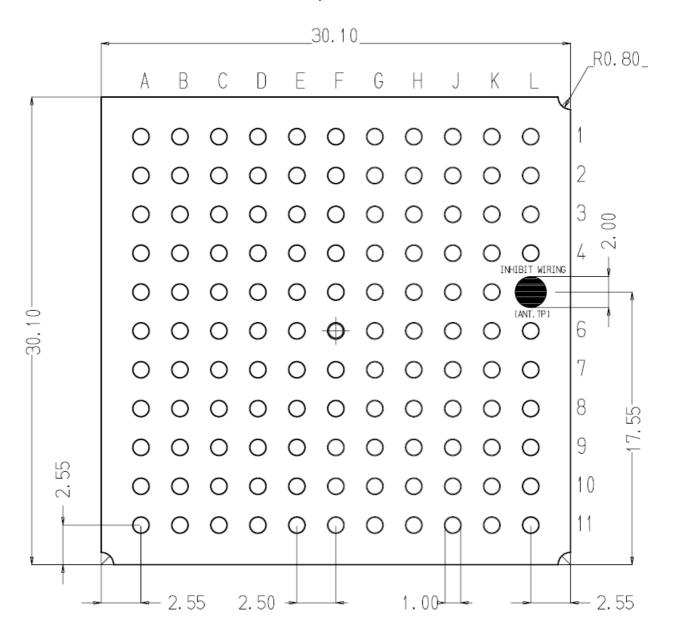




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## 14.1.3. Recommended Foot Print for the Application (GE864)

## Top view





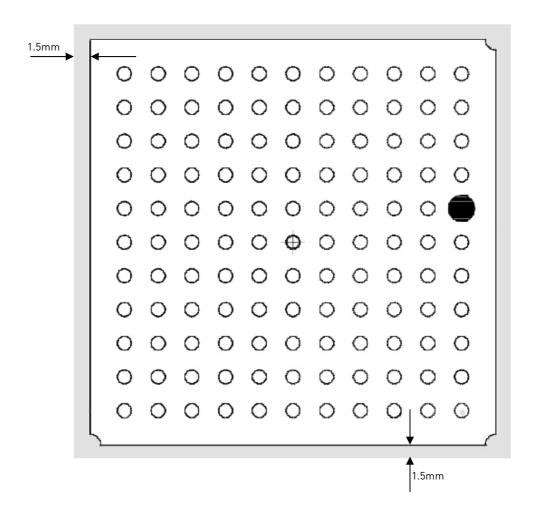


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## 14.1.4. Suggested Inhibit Area

In order to easily rework the GE864 is suggested to consider on the application a 1.5mm Inhibit area around the module:

#### Top view



It is also suggested, as common rule for an SMT component, to avoid having a mechanical part of the application in direct contact with the module.



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## 14.1.5. Debug of the GE864 in Production

To test and debug the mounting of the GE864, we strongly recommend to foreseen test pads on the host PCB, in order to check the connection between the GE864 itself and the application and to test the performance of the module connecting it with an external computer. Depending by the customer application, these pads include, but are not limited to the following signals:

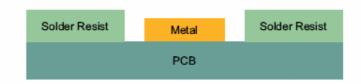
- TXD
- RXD
- ON/OFF
- RESET
- GND
- VBATT
- TX\_TRACE
- RX TRACE
- PWRMON

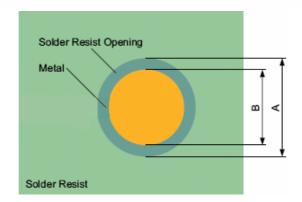
#### 14.1.6. Stencil

Stencil's apertures layout can be the same of the recommended footprint (1:1), we suggest a thickness of stencil foil  $\geq 120\mu m$ .

## 14.1.7. PCB Pad Design

Non solder mask defined" (NSMD) type is recommended for the solder pads on the PCB.







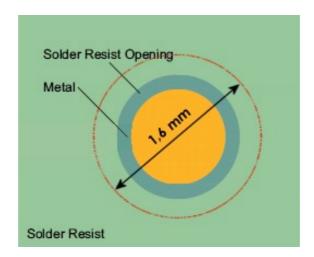


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Recommendations for PCB pad dimensions:

Ball pitch [mm]	2,5
Solder resist opening diameter A [mm]	1,150
Metal pad diameter B [mm]	1 ± 0.05

It is recommended no microvia without solder resist cover under the module and no microvia around the pads (see following figure).



Holes in pad are allowed only for blind holes and not for through holes.

Recommendations for PCB pad surfaces:

Finish	Layer thickness [µm]	Properties
Electro-less Ni /	3 –7 /	good solder ability protection, high
Immersion Au	0.05 – 0.15	shear force values

The PCB must be able to resist the higher temperatures which are occurring at the lead-free process. This issue must be discussed with the PCB-supplier. Generally, the wettability of tin-lead solder paste on the described surface plating is better compared to lead-free solder paste.

#### 14.1.8. Solder Paste

	Lead free
Solder paste	Sn/Ag/Cu

It is recommended to use only "no clean" solder paste in order to avoid the cleaning of the modules after assembly.

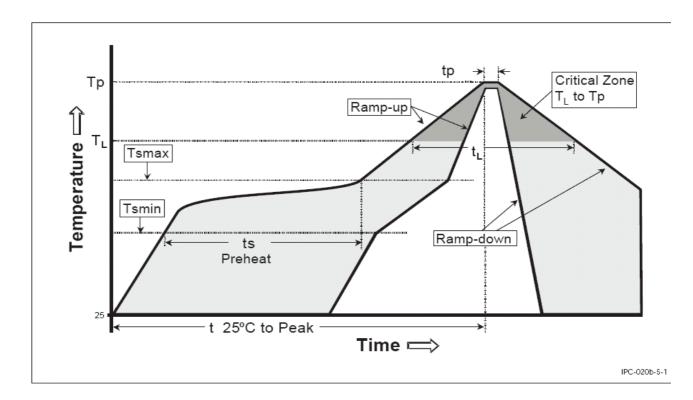




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## 14.1.9. GE864 Solder Reflow

The illustration below shows the recommended solder reflow profile:



Profile Feature	Pb-Free Assembly
Average ramp-up rate (T <sub>L</sub> to T <sub>P</sub> )	3°C/second max
Preheat	
8 Temperature Min (Tsmin)	150°C
8 Temperature Max	200°C
(Tsmax)	60-180 seconds
- Time (min to max) (ts)	
Tsmax to TL	
– Ramp-up Rate	3°C/second max
Time maintained above:	
8 Temperature (TL)	217°C
- Time (tL)	60-150 seconds
Peak Temperature (Tp)	245 +0/-5°C
Time within 5°C of actual Peak	10-30 seconds
Temperature (tp)	
Ramp-down Rate	6°C/second max.
Time 25°C to Peak Temperature	8 minutes max.

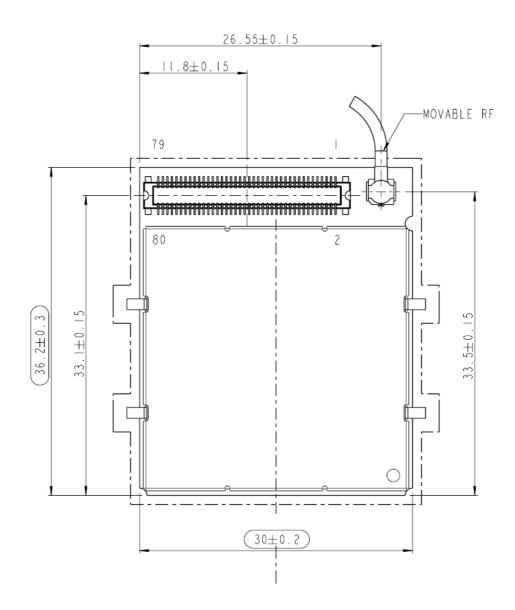




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## 14.2. GC864-QUAD

The position of the Molex board to board connector and the pin 1 are shown in the following picture.





#### NOTE:

The metal tabs present on GC864-QUAD must be connected to GND.

This module could not be processed with a reflow.





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#### 14.2.1. Debug of the GC864-QUAD in Production

To test and debug the mounting of the GC864, we strongly recommend to foreseen test pads on the host PCB, in order to check the connection between the GC864-QUAD itself and the application and to test the performance of the module connecting it with an external computer. Depending by the customer application, these pads include, but are not limited to the following signals:

- TXD
- RXD
- ON/OFF
- RESET
- GND
- VBATT
- TX\_TRACE
- RX TRACE
- PWRMON

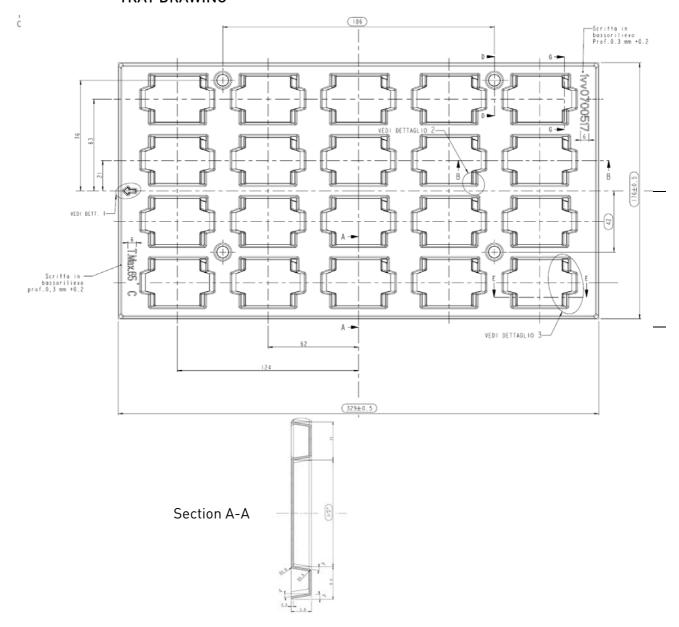


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## 14.3. Packing System

The Telit modules are packaged on trays of 20 pieces each. This is especially suitable for the GE864 modules according to SMT processes for pick & place movement requirements.

#### TRAY DRAWING



The size of the tray is: 329 x 176mm



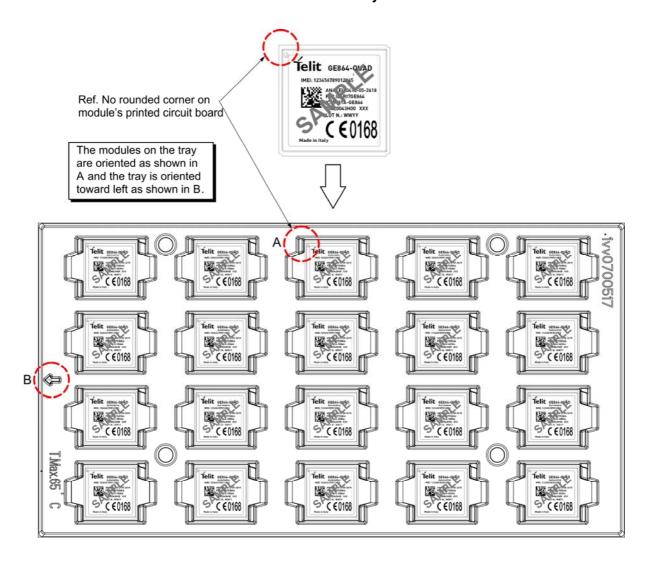




#### **WARNING:**

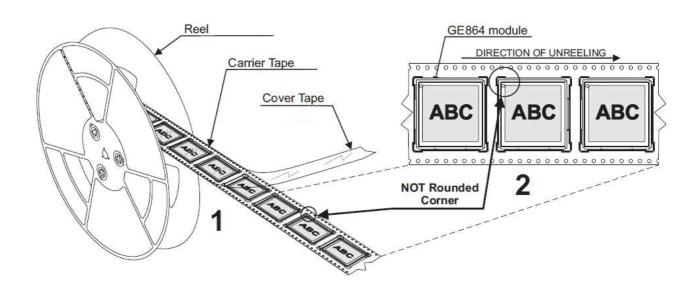
These trays can withstand the maximum temperature of  $65^{\circ}$  C.

## 14.3.1. GE864 Orientation on the Tray





## Reel Drawing



## 14.3.2. Moisture Sensibility

The level of moisture sensibility of GE864 module is "3", in according with standard IPC/JEDEC J-STD-020, take care all the relatives requirements for using this kind of components.



## 15. Conformity Assessment Issues

The Telit GE864/GC864 has been assessed in order to satisfy the essential requirements of the R&TTE Directive 1999/05/EC (Radio Equipment & Telecommunications Terminal Equipments) to demonstrate the conformity against the harmonized standards with the final involvement of a Notified Bodies, depending on the product's P/N.

## **C €** 0889

If the module is installed in conformance to the Telit installation manuals, no further evaluation under Article 3.2 of the R&TTE Directive and do not require further involvement of a R&TTE Directive Notified Body for the final product. In all other cases, or if the manufacturer of the final product is in doubt, then the equipment integrating the radio module must be assessed against Article 3.2 of the R&TTE Directive.

In all cases the assessment of the final product must be made against the Essential requirements of the R&TTE Directive Articles 3.1(a) and (b), Safety and EMC respectively, and any relevant Article 3.3 requirements.

This Product Description, the Hardware User Guide and Software User Guide contain all the information you may need for developing a product meeting the R&TTE Directive.

Furthermore the GE864/GC864 is FCC Approved as modules to be installed in other devices. These devices are to be used only for fixed and mobile applications. If the final product after integration is intended for portable use, a new application and FCC is required.

The GE864 is conforming to the following US Directives:

- Use of RF Spectrum. Standards: FCC 47 Part 24 (GSM 1900)
- EMC (Electromagnetic Compatibility). Standards: FCC47 Part 15

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions:

- (1) this device may not cause harmful interference, and
- (2) this device must accept any interference received, including interference that may cause undesired operation.

To meet the FCC's RF exposure rules and regulations:





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- The system antenna(s) used for this transmitter must be installed to provide a separation distance of at least 20 cm from all the persons and must not be colocated or operating in conjunction with any other antenna or transmitter.
- The system antenna(s) used for this module must not exceed 1.4dBi (850MHz) and 3.0dBi (1900MHz) for mobile and fixed or mobile operating configurations.
- Users and installers must be provided with antenna installation instructions and transmitter operating conditions for satisfying RF exposure compliance.

Manufacturers of mobile, fixed or portable devices incorporating this module are advised to clarify any regulatory questions and to have their complete product tested and approved for FCC compliance.



## SAFETY RECOMMENDATIONS



#### NOTE:

Read this section carefully to ensure the safe operation.

Be sure the use of this product is allowed in the country and in the environment required. The use of this product may be dangerous and has to be avoided in the following areas:

- Where it can interfere with other electronic devices in environments such as hospitals, airports, aircrafts, etc
- Where there is risk of explosion such as gasoline stations, oil refineries, etc

It is responsibility of the user to enforce the country regulation and the specific environment regulation.

Do not disassemble the product; any mark of tampering will compromise the warranty validity.

We recommend following the instructions of the hardware user guides for a correct wiring of the product. The product has to be supplied with a stabilized voltage source and the wiring has to be conforming to the security and fire prevention regulations.

The product has to be handled with care, avoiding any contact with the pins because electrostatic discharges may damage the product itself. Same cautions have to be taken for the SIM, checking carefully the instruction for its use. Do not insert or remove the SIM when the product is in power saving mode.

The system integrator is responsible of the functioning of the final product; therefore, care has to be taken to the external components of the module, as well as of any project or installation issue, because the risk of disturbing the GSM network or external devices or having impact on the security. Should there be any doubt, please refer to the technical documentation and the regulations in force.

Every module has to be equipped with a proper antenna with specific characteristics. The antenna has to be installed with care in order to avoid any interference with other electronic devices and has to guarantee a minimum distance from the body (20 cm). In case of this requirement cannot be satisfied, the system integrator has to assess the final product against the SAR regulation EN 50360.



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The European Community provides some Directives for the electronic equipments introduced on the market. All the relevant information's are available on the European Community website:

http://ec.europa.eu/enterprise/sectors/rtte/documents/

The text of the Directive 99/05 regarding telecommunication equipments is available, while the applicable Directives (Low Voltage and EMC) are available at:

http://ec.europa.eu/enterprise/sectors/electrical/